# **Dispersion and dissipation in bore propagation**

Inria at University of Bordeaux



in natural and artificial channels: what are we modelling ?

#### M. Ricchiuto

# Workshop on bedload and sedimentation processes

experiments, modelling and numerical simulation

January 27-28 Sevilla, Spain

- P. Bonneton (CNRS)
- **R. Chassagne** (U. Grenoble)
- **A.G. Filippini** (BRGM)
- S. Gavrilyuk (U. Aix-Marseille)
- **B. Jouy** (EDF)
- M. Kazolea (Inria)
- M. Le (LHSV)
- H. Ranocha (Mainz U.)
- **D. Violeau** (EDF)

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credit to them for the good stuff, blame me for the rest



#### Amazon river (Brazil)



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# Side 1: real life







Garonne river (France)













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# Side 1: real life

#### Manosque plant, France (Courtesy of EDF)



# Hydrodynamics

- strong acceleration at the front
- vertical and horizontal kinematics
- turbulent flow (breaking)



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# Side 1: real life

# Hydro-sedimetary processes

- resuspension of bottom sediments
- diffusion across the water column
- diffusion across the section





#### Delicate equilibrium between

- nonlinearity
- dispersion
- dissipation

$$\partial_t u = -\partial_x f(u) + \alpha \partial_{txx}$$

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#### Side 2: math



 $u_x u + \beta \partial_{xxx} u + \partial_x (\mu \partial_x u) - \sigma u$ 





#### Hyperbolic shallow water

- discontinuous data -> genuine shocks
- discontinuous weak solutions
- admissible (viscosity) solutions !

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# Side 2: math



#### **Dispersive Serre-Green-Naghdi**

- discontinuous data -> dispersive shocks
- continuous (high frequency) solutions
- admissibility/uniqueness: no need to invoke viscosity





















Talk Part I : can hyperbolic models also provide dispersive shocks ?

O yes, whenever small scale heterogeneity is there. In multiD -> bathymetric variations

O these dispersive-like undular bores occur systematically fin real life for Froude numbers below ~ 1.15-1.17

O dispersive (transverse averaged) models are constructed











Talk Part II (only if time): quid of the notion of viscosity solution ?

O open question ... energy is ALWAYS conserved when (physical) dispersion is active

O in practice: numerical dissipation significantly alters (negatively) simulation results, also in presence of physical dissipation

**O examples are provided** 









# **Undular bores:** straight walled channels, estuaries, and man made channels

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#### **Experiments in rectangular channels (no banks)**



"dispersive bore" or "Favre wave"

Favre, Dunod, 1935 Treske, J. Hydraulic Research, 1994 F<sub>t2</sub>>*Fr*>1

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# **Experimental studies**



$$F_{t2}$$
  $Fr > F_{t2}$ 



#### **Experiments in rectangular channels (no banks)**



Treske, J. Hydraulic Research, 1994

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# **Experimental studies**







#### **Experiments in rectangular channels (no banks)**



Treske, J. Hydraulic Research, 1994

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### **Experimental studies**

Fr





# Lemoine analogy

Lemoine, La Houille Blanche, 1948

- 1. Secondary waves conserve mass/momentum
- 3. No energy dissipation, energy goes into the secondary waves

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# Lemoine analogy



2. The undular front moves at the speed of the bore:  $C_b = U_2 + C_\lambda$ 



# Lemoine analogy

Lemoine, La Houille Blanche, 1948

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# Lemoine analogy



# 2. The undular front moves at the speed of the bore: $C_b = U_2 + C_\lambda$





#### **Bore:**

Shallow water Rankine-Hugoniot relation (no dispersion !!):

$$C_b - U_2 = \sqrt{rac{h_1}{h_2}grac{h_1+h_2}{2}}$$

 $C_b = U_2 + C_\lambda \implies \lambda(Fr)$ 

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# Lemoine analogy





$$C_{\lambda} = \sqrt{g \frac{\lambda}{2\pi} \tanh\left(\frac{2\pi}{\lambda}h\right)}$$





 $C_b = U_2 + C_\lambda \Longrightarrow \lambda(Fr)$ 



# Lemoine analogy





Fig. 8. Undular bore at Froude  $\sim 1.04$ .



Fr

Fig. 9. Undular bore at Froude  $\sim 1.06$ .



Fig. 10. Undular bore at Froude ~ 1.10.



Treske, J. Hydraulic Research, 1994

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# **Treske's experiments**



 $F_{t1} < Fr < F_{t2}$ *Fr*>F<sub>t2</sub> F<sub>t2</sub> Fr





Fig. 8. Undular bore at Froude  $\sim 1.04$ .



Fig. 9. Undular bore at Froude ~ 1.06.



Fig. 10. Undular bore at Froude  $\sim 1.10$ .



Fr

Treske, J. Hydraulic Research, 1994

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## **Treske's experiments**



Fig. 13. Bore at Froude ~ 1.35.





Treske, J. Hydraulic Research, 1994



# **Treske's experiments**



#### **EDF Chatou's flume**



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# **Jouy's experiments**









# Low Fr transition in Seine and Gironde: the invisible Mascaret

3 field campaigns :

a unique long-term high-frequency database





Bonneton et al, Comptes Rendus Geoscience, 2012Bonneton et al, J. Geophysical Research - Oceans, 2015

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# Field studies: Gironde and Seine









# Field studies: Gironde and Seine







# **Field studies: Gironde and Seine**







The occurrence of these tidal jumps is enormously underestimated. According to **Bonneton et al**, J.Coast.Res. 2011

- In the Garonne river they may appear for 90% of tides during low flow period - In the Seine river, bores were thought to have disappeared due to dredging

Tidal jumps still involve significant acceleration at the front and could have important impact on sediment dynamics.

These bores do not agree with the Lemoine analogy using the classical dispersive wave (Airy) theory associated to vertical kinematics. They involve other processes

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# Numerical modelling using

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Serre-Green-Nagdhi and Shallow Water (!)

### **Dispersive wave models**



# Physical hypotheses

Long waves : small  $\mu$ 

Weakly dispersive waves :  $\mu^2 \ll 1$  ,

Weak/full non-linearity :  $\epsilon = \mathcal{O}(\mu^2$ 



# **Depth averaged asymptotic models**

#### **Dimensionless parameters**

• dispersion: 
$$\mu = \frac{h_0}{\lambda} = \frac{\kappa h_0}{2\pi}$$
  
• non-linearity:  $\epsilon = \frac{a}{h_0}$ 

, 
$$\mu^4$$
 negligible

$$^2)$$
 and  $\epsilon = \mathcal{O}(1)$  respectively



# Asymptotic expansion, depth averaging

1. Starting point : nonlinear wave equations

$$\partial_t \Phi + \frac{1}{2} \| \nabla \Phi \|^2$$
  
 $\partial_t \zeta + \partial_x$ 

2. Asymptotic dev. wrt :  $u^2 = a$ 

3. VERTICAL averaging :

$$\int_{0}^{h_0+\zeta} (\cdot) \, dz$$

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# **Depth averaged asymptotic models**

Boussinesq, J.Math. Pures Appl., 1872

**Dingemans,** World Scientific, 1997

Lannes, AMS, 2013

Lannes, Nonlinearity, 2020

 $+g\zeta = 0$ 

 $\Delta \Phi = 0$ 

 $\partial_{z} \Phi = 0$ 

 $\mu^2 \Phi = \Phi_0 + \mu^2 \Phi_1 + \mu^4 \Phi_2 + \dots$ 

$$h\vec{\mathbf{u}} = \int_{b}^{\zeta} \vec{\mathbf{v}} \, dz$$



Shallow water equations in 1D

# $\partial_t h + \partial_x (h\mathbf{u}) = 0$ $\partial_t (h\mathbf{u}) + \partial_x (h\mathbf{u}^2 + gh^2/2) + gh\partial_x b = \mathcal{D}$





# **Depth averaged asymptotic models**

 $\mathcal{D} = 0$ : usual shallow water eqs.  $\mu = 0$  limit, or equivalently zero-th order term in the expansion





#### Serre Green-Naghdi equations in 1D

$$\partial_t h + \partial_x (h \mathbf{u}) =$$
  
 $\partial_t (h \mathbf{u}) + \partial_x (h \mathbf{u}^2 + d_x)$ 

$$\mathcal{D} = \partial_x \left(\frac{h^3}{3} \partial_x \dot{\mathbf{u}}\right) - \partial_x \left(\frac{\partial_x b}{2} h^2 \dot{\mathbf{u}}\right) - h(\partial_x dx)$$

$$-\frac{2}{3}\partial_x(h^2(\partial_x\mathsf{u})^2+\frac{3}{4}h^2\mathsf{u}^2\partial_{xx}b)-\frac{h^2}{4}d^2(\partial_x\mathsf{u}^2)^2+\frac{3}{4}h^2\mathsf{u}^2\partial_{xx}b)-\frac{h^2}{4}d^2(\partial_x\mathsf{u}^2)^2+\frac{3}{4}h^2\mathsf{u}^2\partial_{xx}b^2+\frac{h^2}{4}h^2+\frac{h^2}{4}h^2+\frac{$$

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# **Depth averaged asymptotic models**

# = 0 $-gh^2/2) + gh\partial_x b = \mathcal{D}$

 $(b)^2 \dot{\mathsf{u}}$ 

$$\mu^2$$
 correction, with  $\dot{\mathbf{u}} = \partial_t \mathbf{u} + \mathbf{u} \partial_x \mathbf{u}$ 

 $rac{h\mathsf{u}^2}{2}\partial_x(\partial_x b)^2$ 

Green & Naghdi, J.Fluid Mech, 1976

Chazel et al, J.Sci.Comp. 2011

Lannes, Nonlinearity 2020







#### Serre Green-Naghdi equations in 1D

$$\partial_t h + \partial_x (h \mathbf{u}) =$$
  
 $\partial_t (h \mathbf{u}) + \partial_x (h \mathbf{u}^2 + d_x)$ 

$$\mathcal{D} = -\partial_x \left(\frac{h^2}{3}\ddot{h}\right) - \partial_x \left(\frac{h^2}{2}\dot{\kappa}\right) - h\left(\frac{\ddot{h}}{2} + h\right)$$

with

$$\kappa = u\partial_x b$$

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# **Depth averaged asymptotic models**

# = 0 $-gh^2/2) + gh\partial_x b = \mathcal{D}$

 $\dot{\kappa})\partial_x b$ 

$$\mu^2$$
 correction, with  $\dot{\mathbf{u}} = \partial_t \mathbf{u} + \mathbf{u} \partial_x \mathbf{u}$ 

Green & Naghdi, J.Fluid Mech, 1976 Chazel et al, J.Sci.Comp. 2011 Lannes, Nonlinearity 2020







# **Dispersive wave models**



# Depth averaged asymptotic models





# Multi dimensional (and other) extension

See e.g. the book by D. Lannes (AMS 2013) or

Shi et al, Ocean Mod 2012

Lannes and Marche, J.Comput.Phys., 2015

Lannes, Nonlinearity, 2020

Gavrilyuk and Shyue, J.Hyd.Res., 2023

We use the formulations discussed in

Filippini et al, J.Comput.Physi. 2016

Kazolea et al, Ocean Mod. 2023

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## **Depth averaged asymptotic models**





$$\partial_t A(h) + \partial_x (A(h)U) = 0$$
  
 $\partial_t (A(h)U) + \partial_x (A(h)U^2 + K(h)) = 0$   
 $\partial K = gh\partial A$ 

for a trapezium

$$A(h) = Wh + \frac{h^2}{\tan\theta}$$
$$K(h) = Wg \frac{h^2}{2} + \frac{g}{\tan\theta} \frac{h^3}{3}$$

Smoothed initial discontinuous state from Rankine-Hugoniot condition of classical section averaged shallow water system for different Froude numbers

Chanson, Elsevier, 2024





# 2D simulations (trapezoidal)

#### Fr = 1.10



# Fr = 1.17



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# **Treske's experiments**


### **2D simulations (trapezoidal)**

#### Fr = 1.10





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#### **Treske's experiments**



#### **2D simulations (trapezoidal)**







#### **Treske's experiments**



- - - - Lemoine theory (SGN)

- SGN banks + Treske banks
- SGN axis x Treske axis



Several elements hint that it may be an hydrostatic process:

- It is predominant on the banks (very shallow limit)
- It involves long(er) waves
- Previous work on dispersion in wave propagation in heterogenous media:

Berezovski et al, Acta Mechanica 2011

Berezovski et al, Int.J.Solid and Structures 2013

Ketcheson & Quessada de Luna, SIAM Multiscale Mod. Simul., 2015

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#### **Dispersive-like waves**



- - - - Lemoine theory (SGN)

- SGN banks + Treske banks
- SGN axis x Treske axis



#### **2D simulations (trapezoidal)**

#### Shallow water simulations with different codes for Fr = 1.05



Fr = 1.05



UHAINA, by the French Geophysical survey www.brgm.fr



#### SLOWS, developed by inria

gitlab.inria.fr/slows-public-group/slows\_public



#### Eole-SW, developed by PRINCIPIA www.principia-group.com



#### **2D simulations (trapezoidal)**



Fr = 1.05

#### **Dispersive waves described by the hyperbolic shallow water eq.s** !

With a discontinuous initial state !

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#### **Dispersive-like waves**





A geometrical fully nonlinear dispersive model for (weakly) dispersive-like waves in channels

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Result from **Chassagne et al**, JFM 2019 : under appropriate scaling assumptions a 1D transverse averaged wave equation from the 2D linearized SW equations with prismatic section

The above model predicts within quite some quantitative accuracy the wavelengths for the low Froude waves (cf later).

We describe here a fully nonlinear variant (joint work with S. Gavryliuk)

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#### **Dispersive like**



$$\partial_t h + \partial_x (hu) + \partial_y (hv)$$
  
 $\partial_t (hu) + \partial_x (hu^2 + gh^2)$   
 $\partial_t (hv) + \partial_x (huv) + \partial_v (huv)$ 



#### **Dispersive like**



Smallness ansatz (all is along y here !!!)



 $L = \tau_x \sqrt{gh_0}$ 

 $\ell = \tau_y \sqrt{gh_0} \ll L$ 



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#### **Dispersive like**





Smallness ansatz (all is along y here !!!)

$$b^* = bh_0 , \quad \zeta^* = \zeta h_0 , \quad d^* = h_0 d$$
  
$$c^* = xL , \quad y^* = y\ell = \varepsilon yL , \quad t^* = t \frac{L}{\sqrt{gh_0}}$$

$$b^* = bh_0$$
,  $\zeta^* = \zeta h_0$ ,  $d^* = h_0 d$   
 $x^* = xL$ ,  $y^* = y\ell = \varepsilon yL$ ,  $t^* = t \frac{L}{\sqrt{g\hbar}}$ 

$$u^* = \sqrt{gh_0} , \quad v^* = \varepsilon \sqrt{gh_0}$$

$$\varepsilon = \ell/L \ll 1$$

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#### **Dispersive like**



It is assumed that

$$hv(t, x, y = \ell) = hv(t, x, y = -\ell)$$

valid for

- straight walls (v = 0)
- periodicity
- banks (h=0)







Transverse averaging

$$\overline{(\cdot)} = \frac{1}{2\ell} \int_{-\ell}^{\ell} (\cdot)(t, x, y) dy$$

Favre transverse averaging

$$\langle \cdot \rangle = \frac{1}{2\ell \bar{h}} \int_{-\ell}^{\ell} h(t, x, y)(\cdot)(t, x, y) dy$$

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In general even for prismatic channels

$$\ell = \ell(x, t)$$

following e.g. Peregrine JFM 1968, Teng and Wu JFM 1992 we assume  $\ell = const$ 

- exact for straight walls and
- exact for periodic b(y)
- for banks we accept a small geometrical approximation (cf. asymptotic analysis later)

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#### **BCs. and transverse average**







Additional assumption: wide channel wrt depth (rivers, human made channels)

$$\frac{b-\overline{b}}{\overline{h}} = \mathcal{O}(\varepsilon^{\gamma}), \ \gamma > 0$$

For trapezoidal sections equivalent to

$$\frac{b_0}{w\,\tan\theta} = \mathcal{O}(\epsilon^{\gamma})$$

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Dimensionless eq.s and exact averages

$$\begin{split} h_t + (hu)_x + (hv)_y &= 0, \\ u_t + uu_x + vu_y + (h+b)_x &= 0, \\ \varepsilon^2 (v_t + uv_x + vv_y) + (h+b)_y &= 0, \end{split}$$

lead to

$$\begin{split} \overline{h}_t &+ (\overline{h} \langle u \rangle)_x = 0, \\ (\overline{h} \langle u \rangle)_t &+ \overline{(\overline{hu^2} + \frac{1}{2} \overline{h^2})_x} = 0, \\ h &+ b = \overline{h} + \overline{b} - \varepsilon^2 \left\{ \int_{-1}^y \frac{Dv}{Dt} ds - \overline{\int_{-1}^y \frac{Dv}{Dt} ds} \right\} \end{split}$$

$$\begin{split} h_t + (h\langle u \rangle)_x &= 0, \\ (\overline{h}\langle u \rangle)_t + \left(\overline{hu^2} + \frac{1}{2}\overline{h^2}\right)_x = 0, \\ h + b &= \overline{h} + \overline{b} - \varepsilon^2 \left\{ \int_{-1}^y \frac{Dv}{Dt} ds - \overline{\int_{-1}^y \frac{Dv}{Dt} ds} \right\} \end{split}$$

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#### Averaged equations



Velocity profiles 1

Integrating in y we get:

 $u = \langle u \rangle + \varepsilon^2 \left\{ \int_{-1}^{g} v_x ds - \left\langle \int_{-1}^{g} v_x ds \right\rangle \right\}$ 

Leading to

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 $hu^2 = h\langle u \rangle^2 + \mathcal{O}(\varepsilon^4)$ 





Velocity profiles 2

$$h+b = \overline{h} + \overline{b} - \varepsilon^2 \left\{ \int_{-1}^{y} \frac{Dv}{Dt} ds - \int_{-1}^{y} \frac{ds}{Dt} ds - \int_{-1}^{y} \frac{Dv}{Dt} ds - \int_{-1}^{y} \frac{Dv}{Dt} ds \right\}$$

$$v = (\overline{S} - S)\langle u \rangle_x + C$$







Velocity profiles 2

$$h+b = \overline{h} + \overline{b} - \varepsilon^2 \left\{ \int_{-1}^{y} \frac{Dv}{Dt} ds - \int_{-1}^{y} \frac{ds}{Dt} ds - \int_{-1}^{y} \frac{Dv}{Dt} ds - \int_{-1}^{y} \frac{Dv}{Dt} ds \right\}$$

$$v = (\overline{S} - S)\langle u \rangle_x + C$$

**REMARK** For symmetric channels  $\overline{S}=0\,$  which allows to show  $\,v(-\ell)=v(\ell)=\mathcal{O}(arepsilon^2)$ In this case geometrical (on  $\ell$  ) and BCs errors are bounded by  ${\cal O}(arepsilon^2)$ 

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#### Dispersive-like behaviour

We can now compute

$$\overline{h^2} = \overline{h}^2 + 2\varepsilon^2 \frac{d\sigma}{dy} \mathbb{N}$$

where 
$$\sigma(y)=\overline{S}-S(y)$$
 and (setting  $au=1/\overline{h}$  and  $\dot{ au}=\partial_t au+\langle u
angle\partial_x au$ )

$$\mathsf{M} = \int_{-1}^{y} \left( \frac{\sigma(y')}{1 - \tau \frac{d\sigma(y')}{dy'}} \ddot{\tau} + \frac{\sigma(y') \frac{d\sigma(y')}{dy'}}{\left(1 - \tau \frac{d\sigma(y')}{dy}\right)^2} \dot{\tau}^2 \right) dy' + \frac{\sigma^2(y)}{2\left(1 - \tau \frac{d\sigma(y')}{dy}\right)^2} \dot{\tau}$$

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#### **Velocity profiles**

# $\frac{\sigma}{2}$ M + const + $\mathcal{O}(\varepsilon^4)$





#### Lagrangian structure

For symmetric channels

$$\frac{d\sigma}{dy}\mathsf{M} = -\frac{\delta\mathcal{L}}{\delta\tau} :=$$

with

$$\mathcal{L} = \frac{\overline{d\sigma}}{dy} \mathbf{N} , \quad \mathbf{N} = \frac{\dot{\tau}}{\dot{z}}$$

and with the abuse of notation

 $\dot{f} = \frac{Df}{Dt} = \partial_t f + \langle u \rangle \partial_x f$ 

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 $= -\left(\partial_{\tau}\mathcal{L} - \frac{D}{Dt}(\partial_{\dot{\tau}}\mathcal{L})\right)$ 

 $\frac{\dot{\tau}^2}{2} \int_{-1}^{y} \frac{\sigma(y')}{1 - \tau \frac{d\sigma(y')}{dy'}} dy'$ 





#### Lagrangian structure: simplified model

For symmetric wide/shallow channels

$$\mathcal{L} = -\overline{S^2} \frac{\dot{\tau}^2}{2}$$

with 
$$S=\int_{-1}^{y}(ar{b}-b(y'))dy'$$
 and now  $\overline{\Delta L}$ 











#### (simplified) Geometrical Green-Naghdi equations

Neglecting small terms we obtain the system of equations for tansverse averaged depth and velocity (averages removed for simplicity)

$$h_t + (hu)_x = 0$$
$$(hu)_t + (hu^2 + gh^2)$$
$$E(h, u)_t + F(h, u)_x = 0$$



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#### **Averaged equations**



**V** 

# $(2+p)_x = 0$



#### Model properties

- Galilean invariance
- Variational (Lagrangian) formulation and the energy conservation law
- Exhibits several families of travelling wave solutions (solitons, periodic, composite)
- Physically relevant dispersion relation (cf. next)
- Consistent with all relevant BCs, and hypotheses (for practical interest: banks and walls)

More in S. Gavrilyuk and M. Ricchiuto, A geometrical Green-Naghdi type system for dispersive-like waves in prismatic channels, <a href="https://arxiv.org/abs/2408.08625">https://arxiv.org/abs/2408.08625</a>, in revision on Journal of Fluid Mechanics

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## Rankine Hugoniot (non-dispersive) —> $C_b = U_2 + C_\lambda$ <— Phase celerity



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#### **Dispersive properties**







#### **Dispersive properties**

$$rac{h_2}{h_1}=1.125\,,~~\chi=0$$
 (no bathymetry)



#### 2D shallow water simulations (mesh converged)

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#### Numerical test: Riemann problem

$$\frac{h_2}{h_1} = 1.125 \,, \ \chi = 0.6 \text{m}^4$$





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#### Numerical test: Riemann problem





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#### Numerical test: Riemann problem







Fig. 8. Undular bore at Froude ~ 1.04.



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Fig. 9. Undular bore at Froude ~ 1.06.



Fig. 10. Undular bore at Froude ~ 1.10.



#### Favre experiment



Fig. 11. Undular bore at Froude ~ 1.12.



Fig. 12. Undular bore at Froude ~ 1.24.



Fig. 13. Bore at Froude ~ 1.35.



$$\bar{h}(x) = \bar{h}_1 + \frac{\bar{h}_2 - \bar{h}_1}{2}(1 - \tanh(x/\alpha))$$
$$u(x) = \frac{u_2}{2}(1 - \tanh(x/\alpha))$$

- $\overline{h}_1\,,\ \overline{h}_2\,$  from jump conditions of non dispersive limit
- S(y) evaluated using the post-bore section height
- Froude numbers from 1.0125 to 1.20

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#### **Favre experiment**







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#### **Favre experiment**









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## Energy stability

#### VS

## **Energy conservation**



- Hyperbolics : thermodynamics and viscous regularisations agree and allow to provide physically correct notion of dissipative solutions
- several different schemes for complex systems of PDEs
- Dispersive models: notion of admissible solutions of initially discontinuous data purely geometrical (some sort of generalized Lax condition), no notion of dissipation. or **Arnold, Camassa, Ding** St.Appl.Math 2024)

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Work by M.Lukácová-Medvidová and co-workers exploits this for rigorous convergence of

In fact energy is always conserved (see El J. Nonlin. Sci. 2005, Hoefer J. Nonlin. Sci. 2014,

• Energy dissipation for a scheme is a natural stability property, but does not agree with any thermodynamics. It is arguable that one should aim for this property (instead of conservation ..)

#### What does practice tell us ????



In Ranocha & Ricchiuto <u>arxiv.org/abs/2408.02665</u> Num.Meth.PDEs (submitted) framework to obtain mass, momentum, energy conservative schemes for (several variants of) the SGN equations using a combination of

- split form of the equation (combination of conservative/non-conservative)
- summation by parts discrete operators
- arbitrary order approximations (FD, Fourier, FE)

$$\left(\underbrace{\frac{1}{2}gh^2 + \frac{1}{2}hu^2 + \frac{1}{6}h(\dot{h})^2}_{=E}\right)_t + \left(\underbrace{gh^2u + \frac{1}{2}hu^3 + \frac{1}{6}h(\dot{h})^2u + \tilde{p}u}_{=F}\right)_x = 0.$$

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#### **Example 1: Serre-Green-Naghdi equations**

$$\begin{split} h_t + (hu)_x &= 0, \\ (hu)_t + \left(hu^2 + \frac{1}{2}gh^2 + \tilde{p}\right)_x &= 0, \\ \tilde{p} &= -\frac{1}{3}\left(h^3(\dot{u})_x - 2h^3u_x^2\right), \end{split}$$



In Jouy et al Appl.Math.Mod 2024 non-dissipative approximation for the Boussinesq equations by Winckler and Liu J. Fluid.Mech. 2015 (WL model) modelling dispersive waves in channels of arbitrary section, using a combination of

- reformulation as section averaged hyperbolic SWE with a point source satisfying an elliptic PDE
- entropy conservative FV for the section averaged SWEs based on a generalization of Tadmor's shuffle conservation condition
- FE treatment of the elliptic operator





#### **Example 2: Boussinesq model by Wincler and Liu**

# $\partial_t A + \partial_x (Au) = 0$ $\partial_t (Au) + \partial_x (Au^2 + gK) = A\phi$ $\phi - \partial_x(\gamma^*\partial_x\phi) = \partial_x(\gamma^*\partial_x\theta)$

$$egin{aligned} A &= \int_{-\ell}^\ell h(y) dy \;, \;\;\; K = \int A(h) dh + M \ &= \partial_x (\zeta + u^2/2) \end{aligned}$$











#### **Numerics vs physics**





#### **Example: short term, no friction**



For short term propagation there is no visible impact of numerical dissipation for fixed/comparable order/mesh size




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# **Example: long term, no friction**





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# **Example: long term, no friction**

also for high orders ...





## **Example: long term, no friction**

MESH DEPENDENT phase ...







## **Example: very long term, no friction**



WL Diss vs no Diss (EC)

For very long term numerical dissipation stabilizes undular bores with MESH DEPENDENT amplitude and MESH DEPENDENT phase ...







WL Diss vs no Diss (EC), with friction

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### **Example: long term, with friction**

Jouy et al, Appl.Math.Mod. 2024







## **Example: long term, with friction**

WL Diss vs no Diss (EC), with friction EC costs "roughly" as much as Roe-O2

**Jouy,** 2024



# **Conclusions and perspectives**

## Part I: the study of Favre waves has revealed importance of "transverse" dispersion

- "Transverse" dispersion is related to the geometry of the bathymetry
- "Transverse" dispersion is hydrostatic, and is well approximated by the SW equations
- Model for vertical AND horizontal dispersive processes in 1D? What is the transition mechanism?

#### Part II: long time simulations revealed (not surprisingly) the impact of numerical dissipation

- Short times reveal no real impact (unless extremely coarse meshes are used)
- Long times: numerical dissipation stabilises mesh depended waves (also in presence of real dissipation)
- Long times: energy conservative/non-dissipative approaches allow to work on coarse meshes

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### Some take away messages

#### • What notion of stability ? How to concile the two without increasing the computational cost ?



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## **Content of the presentation**

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