

General boundary conditions for the Boussinesq-Abbott model with varying topography

David Lannes¹, Mathieu Rigal²

¹ *Institut de Mathématiques de Bordeaux*

² *Laboratoire Jacques-Louis Lions, Sorbonne Université*

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Supervision : David Lannes and Philippe Bonneton

Long term goal: study extreme waves in littoral area



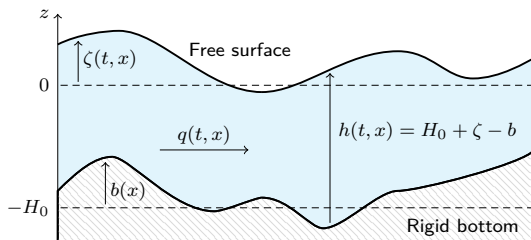
- 1 The model & problematic
- 2 Nonlocal reformulation for flat bottom
- 3 Extention to varying bottom
- 4 Numerical experiment

Boussinesq-Abbott model with varying bottom:

$$\begin{cases} \partial_t \zeta + \partial_x q = 0 \\ (1 + h_b \mathcal{T}) \partial_t q + \partial_x f(\zeta, q) = -gh \partial_x b \end{cases} \quad (\text{BA})$$

with $h_b = H_0 - b$ (depth at rest) and

$$f(\zeta, q) = \frac{q^2}{h} + \frac{gh^2}{2}, \quad h_b \mathcal{T}(\cdot) = -\frac{1}{3} \partial_x (h_b^2 \partial_x \cdot) + \text{lower order terms}$$



Initial-boundary value problem:

$$\begin{cases} \partial_t \zeta + \partial_x q = 0 \\ (1 + h_b \mathcal{T}) \partial_t q + \partial_x f(\zeta, q) = -gh \partial_x b \end{cases} \quad \text{in } (0, \ell) \quad (\text{BA})$$

completed with

$$(\zeta, q)|_{t=0} = (\zeta_0, q_0), \quad \zeta(t, 0) = g_0(t), \quad \zeta(t, \ell) = g_\ell(t)$$

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How to recover $q|_{x=0, \ell}(t)$? (missing data)

- Hyperbolic case ($h_b \mathcal{T} \equiv 0$): Riemann invariants
- Dispersive case: need to invert $(1 + h_b \mathcal{T}) \rightarrow$ requires knowledge on $\partial_t q|_{x=0, \ell}$

- [WKS99] Wei, Kirby, Sinha. "Generation of waves in Boussinesq models using a source function method" (1999)
- [DMS09] Dougalis, Mitsotakis, Saut. "On initial-boundary value problems for a Boussinesq system of BBM-BBM type in a plane domain" (2009)
- [LW20] Lannes, Weynans. "Generating boundary conditions for a Boussinesq system" (2020)
- [BL22] Beck, Lannes. "Freely floating objects on a fluid governed by the Boussinesq equations" (2022)
- [LR24] Lannes, R. "General boundary conditions for a Boussinesq model with varying bathymetry" (2024)

Reformulation of the model (flat bottom)

Flat bottom case ($b \equiv \text{Cst}$): discharge eq. simplifies to

$$(1 - \kappa^2 \partial_{xx}^2) \partial_t q + \partial_x f(\zeta, q) = 0 \quad \text{in } (0, \ell)$$

Fix $0 \leq t \leq T$, then $y(x) = \partial_t q(t, x)$ satisfies an ODE of the form

$$\begin{cases} y - \kappa^2 y'' = \phi(x) \\ y(0) = \dot{q}_{|_0}, \quad y(\ell) = \dot{q}_{|\ell} \end{cases}$$

Equivalently: $y = y_h + y_b$ with $\begin{cases} y_h - \kappa^2 y_h'' = 0 \\ y_h(0) = \dot{q}_{|_0}, \quad y_h(\ell) = \dot{q}_{|\ell} \end{cases}$ and $\begin{cases} y_b - \kappa^2 y_b'' = \phi(x) \\ y_b(0) = y_b(\ell) = 0 \end{cases}$

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Define R^0 as the inverse of $(1 - \kappa^2 \partial_{xx}^2)$ with **homogeneous Dirichlet** conditions at $x = 0, \ell$

$$\Rightarrow \partial_t q = \underbrace{-R^0 \partial_x f}_{y_b} + \underbrace{s_{(0)}(x) \dot{q}_{|_{x=0}} + s_{(\ell)}(x) \dot{q}_{|_{x=\ell}}}_{y_h}$$

where $\begin{cases} (1 - \kappa^2 \partial_{xx}^2) s_{(0)} = 0 \\ s_{(0)}(0) = 1, \quad s_{(0)}(\ell) = 0 \end{cases}$ and $\begin{cases} (1 - \kappa^2 \partial_{xx}^2) s_{(\ell)} = 0 \\ s_{(\ell)}(0) = 0, \quad s_{(\ell)}(\ell) = 1 \end{cases}$. (1)

Reformulation of the model (flat bottom)

Note R^1 the inverse of $(1 - \kappa^2 \partial_{xx}^2)$ with **homogeneous Neumann** conditions at $x = 0, \ell$

$$\Rightarrow R^0 \partial_x = \partial_x R^1$$

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Let (ζ, q) be such that the **compatibility conditions** hold:

$$\begin{cases} \zeta|_{t=0}(0) = g_0(0) \\ -\partial_x q|_{t=0}(0) = \dot{g}_0(0) \end{cases}, \quad \begin{cases} \zeta|_{t=0}(\ell) = g_\ell(0) \\ -\partial_x q|_{t=0}(\ell) = \dot{g}_\ell(0) \end{cases}.$$

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- 2 The pair (ζ, q) satisfies the IVP

$$\begin{cases} \partial_t \zeta + \partial_x q = 0 \\ \partial_t q + \partial_x (R^1 f) = s_{(0)} \dot{q}_{|_0} + s_{(\ell)} \dot{q}_{|\ell} \end{cases} \quad \text{in } (0, \ell), \quad (2)$$

with the trace equations

$$\begin{pmatrix} s'_{(0)}(0) & s'_{(\ell)}(0) \\ s'_{(0)}(\ell) & s'_{(\ell)}(\ell) \end{pmatrix} \begin{pmatrix} \dot{q}_{|_0} \\ \dot{q}_{|\ell} \end{pmatrix} = \frac{1}{\kappa^2} \begin{pmatrix} (R^1 - \text{id})_{|_0} f \\ (R^1 - \text{id})_{|\ell} f \end{pmatrix} - \begin{pmatrix} \ddot{g}_0 \\ \ddot{g}_\ell \end{pmatrix} \quad (3)$$

Proof: \Rightarrow

$$\begin{cases} \partial_t \zeta + \partial_x q = 0 \\ \partial_t q + \partial_x (R^1 f) = s_{(0)} \dot{q}_{l_0} + s_{(\ell)} \dot{q}_{l_\ell} \end{cases}$$

Proof: \Rightarrow

$$\begin{cases} \partial_t \zeta + \partial_x q = 0 \\ \partial_x (\partial_t q + \partial_x (R^1 f)) = s_{(0)} \dot{q}_{|_0} + s_{(\ell)} \dot{q}_{|\ell} \end{cases} \Rightarrow -\partial_{tt} \zeta + \partial_{xx}^2 (R^1 f) = s'_{(0)} \dot{q}_{|_0} + s'_{(\ell)} \dot{q}_{|\ell}$$

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By construction

$$(1 - \kappa^2 \partial_{xx}^2) R^1 = \text{id} \Rightarrow \partial_{xx}^2 R^1 = \kappa^{-2} (R^1 - \text{id})$$

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Taking the trace at $x = 0, \ell$ and using that $\zeta|_{x=0,\ell} = g_{0,\ell}$:

$$\begin{cases} -\ddot{g}_0 + \frac{1}{\kappa^2} (R^1 - \text{id})|_{x=0} f(\zeta, q) = s'_{(0)}(0) \dot{q}_{|_0} + s'_{(\ell)}(0) \dot{q}_{|\ell} \\ -\ddot{g}_\ell + \frac{1}{\kappa^2} (R^1 - \text{id})|_{x=\ell} f(\zeta, q) = s'_{(0)}(\ell) \dot{q}_{|_0} + s'_{(\ell)}(\ell) \dot{q}_{|\ell} \end{cases}$$

Proof: $\boxed{\Leftarrow}$ We now assume that

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Compatibility conditions \Rightarrow solution given by $(\zeta_{l_0}, \zeta_{l_\ell}) = (g_0, g_\ell)$

Possibility to enforce general boundary conditions

$$\xi_0^+(\zeta_0, q_0)(t) = g_0(t), \quad \xi_\ell^-(\zeta_\ell, q_\ell)(t) = g_\ell(t). \quad (4)$$

For instance, ξ^\pm given by q or Saint-Venant Riemann invariants

$$\mathcal{R}_\pm(U) = \frac{q}{h} \pm 2\sqrt{gh}$$

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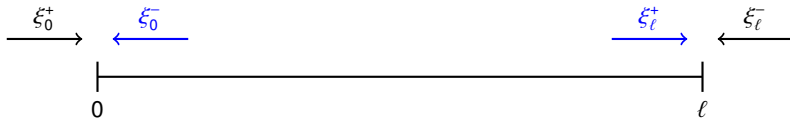
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Adapt trace ODE in terms of **missing data** (outgoing information ξ_0^- and ξ_ℓ^+)

$$\begin{pmatrix} s'_{(0)}(0) & s'_{(\ell)}(0) \\ s'_{(0)}(\ell) & s'_{(\ell)}(\ell) \end{pmatrix} \frac{d}{dt} \begin{pmatrix} q(\xi_0^+, \xi_0^-) \\ q(\xi_\ell^+, \xi_\ell^-) \end{pmatrix} = \frac{1}{\kappa^2} \begin{pmatrix} (R^1 - \text{id})_{l_0} f \\ (R^1 - \text{id})_\ell f \end{pmatrix} - \frac{d^2}{dt^2} \begin{pmatrix} \zeta(\xi_0^+, \xi_0^-) \\ \zeta(\xi_\ell^+, \xi_\ell^-) \end{pmatrix}$$



Case of a varying topography ($b \neq \text{Cst}$)

$$(1 + h_b \mathcal{T}) \partial_t q + \partial_x f(\zeta, q) = -gh \partial_x b$$

where $h_b \mathcal{T}(\cdot) = -\frac{1}{3} \partial_x (h_b^2 \partial_x \cdot) + \text{lower order terms}$

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Note R_b^0 the inverse of $(1 + h_b \mathcal{T})$ with **homogeneous Dirichlet cond.** and

$$\left\{ \begin{array}{l} (1 + h_b \mathcal{T}) \mathfrak{s}_{(b,0)} = 0 \\ \mathfrak{s}_{(b,0)}(0) = 1, \quad \mathfrak{s}_{(b,0)}(\ell) = 0 \end{array} \right. \quad \left\{ \begin{array}{l} (1 + h_b \mathcal{T}) \mathfrak{s}_{(b,\ell)} = 0 \\ \mathfrak{s}_{(b,\ell)}(0) = 0, \quad \mathfrak{s}_{(b,\ell)}(\ell) = 1 \end{array} \right.$$

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$$\Rightarrow \partial_t q = -R_b^0 \partial_x f - g R_b^0 (h \partial_x b) + \mathfrak{s}_{(b,0)} \dot{q}|_0 + \mathfrak{s}_{(b,\ell)} \dot{q}|_\ell$$

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Next step: generalisation of $R^0 \partial_x = \partial_x R^1$?

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$$\#R_b^1 = \left(\sum_{i=0}^2 c_i \partial_x^i \right)^{-1} \quad \text{such that} \quad R_b^0 \partial_x = \partial_x R_b^1$$

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$$\exists R_b^1 = \left(\sum_{i=0}^2 c_i \partial_x^i \right)^{-1} \quad \text{such that} \quad R_b^0 \partial_x = \partial_x R_b^1$$

However we can construct R_b^1 verifying for some $(\alpha, \beta)(x)$

$$R_b^0 (\partial_x + \alpha) = (\partial_x + \beta) R_b^1$$

$$\Rightarrow \partial_t q = -\underbrace{\partial_x R_b^1 f - \beta R_b^1 f + R_b^0 (\alpha f - gh \partial_x b)}_{\mathfrak{B}(\zeta, q)} + \mathfrak{s}_{(b,0)} \dot{q}_{l_0} + \mathfrak{s}_{(b,\ell)} \dot{q}_{l_\ell}$$

Proposition 2 (D. Lannes, R.)

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with the trace equations

$$\begin{pmatrix} s'_{(b,0)}(0) & s'_{(b,\ell)}(0) \\ s'_{(b,0)}(\ell) & s'_{(b,\ell)}(\ell) \end{pmatrix} \begin{pmatrix} \dot{q}|_0 \\ \dot{q}|_\ell \end{pmatrix} + V_{\text{boundary}}(\zeta|_{0,\ell}, q|_{0,\ell}) = V_{\text{interior}}[\zeta, q] - \begin{pmatrix} \ddot{g}_0 \\ \ddot{g}_\ell \end{pmatrix} \quad (6)$$

where V_{boundary} , V_{interior} are known.

- Standard finite differences for nonlocal terms and trace equations
- Finite volumes for interior equations (Lax-Friedrichs or MacCormack)

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Asymptotic stability

Question: starting from a wrong initial condition, can we recover the reference solution by enforcing appropriate boundary conditions?

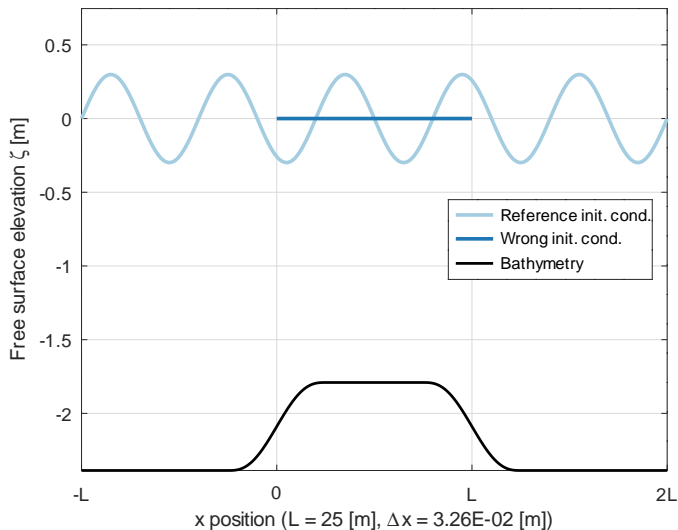


Figure: Sine over bump



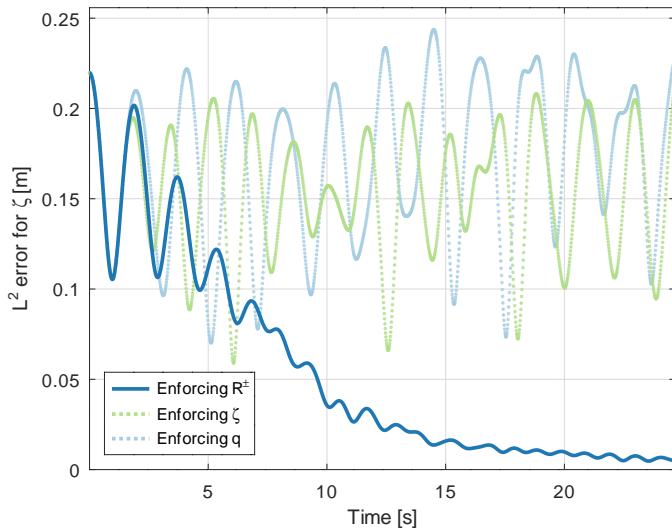


Figure: L^2 error



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- Reformulation strategy allows to recover missing data
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Perspectives: high order DGFEM code, improved dispersion relation

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Thank you for your attention!