# An Ellipsoidal Statistical Model for a monoatomic and polyatomic gas mixture 

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#### Abstract

This paper is devoted to the derivation of an Ellipsoidal Statistical model for a mixture constituted by both monoatomic and polyatomic gases. The non translational degrees of freedom are described by a continous variable and each polyatomic component is allowed to have its own internal degrees of freedom. The construction of the model is based on the moment relaxed method that has been developped in previous works that is generalized in the present paper to a more general setting. More precisely, this method is based on the introduction of free parameters and on the resolution of an entropy minimisation problem. The resulting model satisfies conservation properties and a H theorem. Next, by performing a Chapman-Engskog expansion, the model is shown to recover the right heat transfer coefficient, the shear viscosity and the volume viscosity.


Key words: Kinetic theory, ESBGK model, Polyatomic gas mixture
Subject of classification: 35Q20, 35Q35

## 1 Introduction

In the context of atmospheric reentry, it is necessary to use kinetic models, because in high altitude the Knudsen number can be of order 1. However most of the kinetic models that have been constructed up to now have been developped only for a monoatomic single gas. But in the upper atmosphere the air is made of moleculars like molecular oxygen $\left(O_{2}\right)$ and molecular nitrogen $\left(N_{2}\right)$ which are both diatomic. Moreover the atomic oxygen $(O)$, the atomic nitrogen $(N)$, and the diatomic nitrogen ( $N O$ ) monoxide are also present. Therefore a kinetic description involving in the same time polyatomic and monoatomic gases is necessary. For this modelling, each polyatomic components are represented by a distribution function $f(t, x, v, I)$ depending on time $t$, space $x$, velocity $v$ and on a continous quantum number $I$ ([1]). This last variable collects in particular vibrational and rotational modes. In ([15]), the authors proposed a Boltzmann like collision operator for a single polyatomic gas that is based on the Borgnakke-Larsen procedure ([14]). This means that in each binary interaction, a fraction of the ingoing total energy is attributed to the internal energy of the outgoing pair of molecules and then randomly distributed between the two single particles. This operator is shown to satisfy the right conservation laws and a H theorem. In [25], an existence theorem is proved for the nonlinear collision operator ([15]) in the space homogeneous case. Starting from this model, a compressible Euler system with a general internal energy law has been derived in $([20])$ for a single gas. The generalisation of the collision operator in the context of a polyatomic reacting gas mixture has been performed in ([21]) together with the derivation of a compressible

[^0]Euler system. In ([6]), a Navier-Stokes system has been rigorously constructed starting from a Boltzmann model in the context of a mixture of any monoatomic and any polyatomic components. In particular, in the case of maxwellian and diatomic molecules explicit transport coefficients are computed. In ([4]), the authors derive a two temperature Navier-Stokes system for a polyatomic gas.

In some applications, the complicated Boltzmann collision operator has to be simplified into a BGK model. The principle is to replace the complicated integral operator by a relaxation model while keeping some important physical and mathematical properties: Maxwellian equilibrium states, conservation laws, H theorem. However in the mixture case, even for monoatomic gases, things are not clear. For example, the hydrodynamic limit is much more complicated to handle because there are several transport coefficients and interspecies phenomena like thermal diffusion have to be considered. There are mainly two familly of BGK models for gas mixtures. The first type is based on a unique Maxwellian attractor per species ([2], [16]). The interactions between the particles are modelled by fictitious macroscopic quantites. In particular, in ([2]), these quantities are chosen in order to reproduce the same momentum and energy exchange terms per species like for Maxwell molecules. Moreover [2], is generalized to reactive gas mixtures in ([17], [11] [27]). So when the chemical reactions stop, the model derived in ([17], [11] [27]) correspond to ([2]). In ([40]), the Shakhov model and the ESBGK are improved by introducing fictitious macroscopic velocities in the model. The second type of BGK model is made by a sum of BGK models which reproduce the Boltzmann structure ([5], [13]). In particular, in ([29]), the authors propose a BGK model that is able to reproduce Coulombian cross-sections which is more appropriate for plasma physics applications.

In the present paper, we consider polyatomic gas mixtures. More precisely, we aim to derive from an entropy minimisation problem a BGK model that enables to recover in the same time the shear viscositiy, the volume viscosity and the thermal conductivity coefficient for a mixture of any number monoatomic components and any number of polyatomic components. The question is crucial because in general the authors compute the hydrodynamic limit and eventually compare a posteriori with some existing models. So even if the structure of the fluxes is recovered, the values of the transport coefficients are not correct. By using this minimisation principle, an Ellipsoidal Statistical Model (ESBGK model) ([3], [34]), has been constructed in the monoatomic case in ([18]) and in the polyatomic case in ([19]) for a single gas. Next this technics has been transported to a monoatomic gas mixture ([16], [17]). In ([31]), the authors propose an ESBGK model for a binary polyatomic mixture. In ([36], [37], [41]), existence theorems are proved for the ESBGK model. Hence the main novelty of this paper is the rigorous construction of an Ellpsoidal Statistical Model for a monoatomic and polyatomic gas mixture.

The internal energy variable can also be discrete. For example, a first paper ([33]) incorporates discrete internal degrees of energy in a BGK model. Theses energies correspond in this model to a vibrationnal energy. Moreover, in ([26]), the hydrodynamic limit is studied up to Navier-Stokes system including chemical reactions by starting from a collisional model. In particular, transport coefficients are explicitely computed. Moreover, BGK models have also been derived ([7], [12], [38]) for discrete energy variable. In particular, in ([38]), a generalisation of ([17]) is performed to the polyatomic setting within the formalism of ([26]).

Concerning some applications of such models, we refer to ([24], [32]). In particular, in ([32]) the authors highlight different types of shock profiles that are specific to a polyatomic framework.

The paper is organised as follows. In section 2, the notations that are used in this paper are precised. In particular, hydrodynamic quantities are defined. In section 3, the ESBGK is
constructed by solving an entropy minimisation problem. The model is next shown to satisfy a H theorem and an indifferentiability principle. In section 4, a Chapman-Enskog expansion is performed for the present model and a compressible Navier-Stokes system is obtained. In this part, the relaxation coefficients are detemined in order to fit the thermal conductivity coefficient, the shear viscosity and the volume viscosity. Some concluding remarks and perspectives are summarized in section 5.

## 2 Notations

In the present paper, we consider a mixture of $A$ monoatomic components and $B$ polyatomic components. For $i \in\{1, \ldots, A\}, f_{i}\left(t, x, v_{i}, I_{i}\right)$ represents the distribution function of the $i^{\text {th }}$ component where $v_{i}$ and $I_{i}$ are respectively the velocity and the continous quantum number of the $i^{\text {th }}$ species. The indexes of species are $S_{m}=\{1, \ldots, A\}$ and $S_{p}=\{A+1, \ldots, A+B\}$.
The sets of quantum numbers are

$$
\begin{gathered}
\mathcal{Q}_{i}=\{0\} \quad \text { if } \quad i \in S_{m}, \\
\mathcal{Q}_{i}=\left[0,+\infty\left[\quad \text { if } \quad i \in S_{p}\right.\right.
\end{gathered}
$$

and the associated integration measures $d I_{i}$ are defined by

$$
\begin{aligned}
d I_{i} & =\delta_{i} \quad \text { if } \quad i \in S_{m}, \\
d I_{i} & =m_{+} \quad \text { if } \quad i \in S_{p},
\end{aligned}
$$

where $\delta I_{i}$ is the Dirac distribution and $m_{+}$the Lebesgue measure over $\mathbb{R}_{+}$.
Next, we introduce for $i \in S, \delta_{i}$ as the number of internal degrees of freedom for species $i$. This parameter collects rotational and vibrational modes. For $i \in S_{m}, \delta_{i}=0$ and we use the convention $f_{i}\left(t, x, v_{i}, 0\right)=f_{i}\left(t, x, v_{i}\right)$ in order to be consistent with the monospecies case. In this context, $I_{i}^{2 / \delta_{i}}$ represents the internal energy of the $i^{\text {th }}$ species.
Next, we recall the definition of macroscopic quantities:
The number density of species $i$ (at time $t$ and space $x$ ) is given by

$$
n_{i}=\int_{\mathbb{R}^{3} \times \mathcal{Q}_{i}} f_{i} d v_{i} d I_{i}
$$

$n=\sum_{i \in S} n_{i}$ represents the total number density.
The mass density of species $i \in S$ (at time $t$ and point $x$ )

$$
\rho_{i}=\int_{\mathbb{R}^{3} \times \mathcal{Q}_{i}} m_{i} f_{i} d v_{i} d I_{i},
$$

where $m_{i}$ represents the molecular mass of species $i$.
$\rho=\sum_{i \in S} m_{i} n_{i}$ represents the total mass density.
The momentum of species $i \in S$ (at time $t$ and point $x$ )

$$
\rho_{i} u_{i}=\int_{\mathbb{R}^{3} \times \mathcal{Q}_{i}} m_{i} v_{i} f_{i} d v_{i} d I_{i} .
$$

$\rho u=\sum_{i \in S} \rho_{i} u_{i}$ represents the total momentum.
The total energy of species $i \in S$ (at time $t$ and point $x$ )

$$
\rho_{i} e_{i}=\int_{\mathbb{R}^{3} \times \mathcal{Q}_{i}}\left(m_{i}\left|v_{i}-u\right|^{2}+I_{i}^{2 / \delta_{i}}\right) f_{i} d v_{i} d I_{i} .
$$

Next, the macroscopic internal energy is splitted into a translational and an internal part. So we define the macroscopic translational energy of species $i \in S$ (at time $t$ and point $x$ )

$$
\rho_{i} e_{i, t r}=\int_{\mathbb{R}^{3} \times \mathcal{Q}_{i}} \frac{1}{2} m_{i}\left(v-u_{i}\right)^{2} f_{i} d v_{i} d I_{i}, \quad i \in S .
$$

The macroscopic internal energy of species $i \in S$ (at time $t$ and point $x$ ) writes

$$
\rho_{i} e_{i, \text { int }}=\int_{\mathbb{R}^{3} \times \mathcal{Q}_{i}} I_{i}^{2 / \delta_{i}} f_{i} d v_{i} d I_{i} .
$$

The total energy for the mixture reads

$$
\begin{equation*}
\rho e=\sum_{i \in S} \int_{\mathbb{R}^{3} \times \mathcal{Q}_{i}}\left(\frac{1}{2} m_{i}\left(v_{i}-u\right)^{2}+I_{i}^{2 / \delta_{i}}\right) f_{i} d v_{i} d I_{i}=\rho e_{t r}+\rho e_{i n t}, \tag{2.1}
\end{equation*}
$$

where

$$
\begin{equation*}
e_{t r}=\sum_{i \in S} c_{i} e_{i, t r}, \quad e_{i n t}=\sum_{i \in S} c_{i} e_{i, i n t}, \quad c_{i}=\frac{\rho_{i}}{\rho} . \tag{2.2}
\end{equation*}
$$

$e_{t r}$ represents the translational energy for the mixture and $e_{i n t}$ reprents the internal energy for the mixture.
We define $\delta$ as the number of internal degrees of freedom for the mixture

$$
\begin{equation*}
\delta=\sum_{i \in S} c_{i} \delta_{i} . \tag{2.3}
\end{equation*}
$$

Temperatures are associated to each energy $e, e_{t r}, e_{\text {int }}$ defined in (2.1, 2.2) by $e=\frac{3+\delta}{2} k_{B} T_{e q}$, $e_{t r}=\frac{3}{2} k_{B} T_{t r}, e_{\text {int }}=\frac{\delta}{2} k_{B} T_{\text {int }}$. Hence $T_{\text {eq }}$ writes

$$
\begin{equation*}
T_{e q}=\frac{\frac{3}{2} T_{t r}+\frac{\delta}{2} T_{\text {int }}}{\frac{3}{2}+\frac{\delta}{2}} . \tag{2.4}
\end{equation*}
$$

Moreover $\delta_{i}$ is related to $e_{i, \text { int }}$ by $e_{i, i n t}=\frac{\delta_{i}}{2} k_{B} T_{\text {int }}$. So, the relation (2.2) defining $e_{i n t}$ in function of $e_{i, i n t}$ is consistent with the definition of $\delta$ given in (2.3)

Remark 1. In ([21], [6]), the authors use in kinetic models $\varphi_{i} f_{i}$ instead of $f_{i}$. In that case, $\varphi_{i} f_{i}$ represents the effective distribution function of species $i$. This means that in the definitions of macroscopic quantities, a weight measure $\varphi_{i}$ appears. Moreover, in the Boltzmann operator the cross sections have to be modified accordingly into effective cross sections. We refer to ([6]) for more details and to ([22]) where a comparison of the two formalisms is presented.

Introduce the natural scalar product ([26])

$$
\begin{equation*}
\langle\langle\phi, \psi\rangle\rangle=\sum_{i \in S} \int_{\mathbb{R}^{3} \times \mathcal{Q}_{i}} \phi_{i} \psi_{i} d v_{i} d I_{i}, \tag{2.5}
\end{equation*}
$$

where $\phi$ and $\psi$ are tensors. Consider the vector distribution function $\mathbf{f}$ by

$$
\mathbf{f}=\left(f_{j}\right)_{j \in S} .
$$

and the family of polynomials $\left(\Psi^{1}\right)_{\mathrm{l} \in \mathbf{S}}, \Psi^{\mathrm{mm}}$ and $\Psi^{\mathrm{en}}$

$$
\boldsymbol{\Psi}^{\mathbf{1}}=\left(\delta_{l j}\right)_{j \in S}, \mathbf{l} \in \mathbf{S}, \quad \boldsymbol{\Psi}^{\mathrm{mm}}=\left(m_{j} v_{j}\right)_{j \in S}, \quad \boldsymbol{\Psi}^{\mathbf{e n}}=\left(\frac{1}{2} m_{j}\left|v_{j}-u_{j}\right|^{2}+I_{j}^{2 / \alpha_{j}}\right)_{j \in S}
$$

Then, according to the notation (2.5), the macroscopic quantities write

$$
\rho_{i}=\left\langle\left\langle\mathbf{f}, \boldsymbol{\Psi}^{\mathbf{1}}\right\rangle\right\rangle, \quad \rho u=\left\langle\left\langle\mathbf{f}, \boldsymbol{\Psi}^{\mathrm{mm}}\right\rangle\right\rangle, \quad \rho e=\left\langle\left\langle\mathbf{f}, \boldsymbol{\Psi}^{\mathbf{e n}}\right\rangle\right\rangle
$$

and the Boltzmann entropy is defined by

$$
\begin{equation*}
\mathcal{H}(\mathbf{f})=\langle\langle\mathbf{f} \ln (\mathbf{f})\rangle\rangle . \tag{2.6}
\end{equation*}
$$

The stationary states $\mathcal{M}=\left(\mathcal{M}_{i}\right)_{i \in S}$ of the collision operator presented in ([6]) read

$$
\begin{equation*}
\mathcal{M}_{i}=\frac{n_{i}}{\mathcal{Q}_{i}^{\text {tr }} \mathcal{Q}_{i}^{\text {int }}} \exp \left(-\frac{m_{i}\left|v_{i}-u\right|^{2}+2 I_{i}^{2 / \delta_{i}}}{2 k_{B} T}\right), \quad v_{i} \in \mathbb{R}^{3}, \quad I_{i} \in \mathcal{Q}_{i}, \quad i \in S \tag{2.7}
\end{equation*}
$$

with

$$
\begin{equation*}
\mathcal{Q}_{i}^{t r}=\left(\frac{2 \pi k_{B} T}{m_{i}}\right)^{\frac{3}{2}}, \quad \mathcal{Q}_{i}^{\text {int }}=\int_{\mathcal{Q}_{i}} \exp \left(-\frac{I_{i}^{2 / \delta_{i}}}{k_{B} T}\right) d I_{i} . \tag{2.8}
\end{equation*}
$$

## 3 Construction of an ESBGK model

The aim of this section is to construct an ESBGK model

$$
\partial_{t} f_{i}+v \cdot \nabla_{x} f_{i}=\lambda\left(G_{i}-f_{i}\right), \quad i \in S,
$$

where, the function $G_{i}$ is constructed according to an entropy minimisation principle. The steps of the construction are the following. We firstly define the space of constraints (section 3.2), next the entropy minimisation problem is solved (section 3.3). Finally the model is shown to satisfy a H theorem (section 3.4) and an indifferentiability principle (section 3.5)

### 3.1 Important families of polynomials

In this section, we define polynoms that will be involved in the definition of the space of constraints and in the computation of the hydrodynamic limit. Le us define

$$
\begin{equation*}
\Psi^{\mathrm{pr}}=\left(\Psi_{j}^{p r}\right)_{j \in S}=\left(m_{j}\left(\left(v_{j}-u\right) \otimes\left(v_{j}-u\right)-\frac{1}{3}\left|v_{j}-u\right|^{2} I_{d}\right)\right)_{j \in S}, \tag{3.9}
\end{equation*}
$$

where $I_{d}$ represents the identity matrix on $\mathbb{R}^{3}$,

$$
\begin{gather*}
\Psi^{\mathrm{int}}=\left(\Psi_{j}^{i n t}\right)_{j \in S}=\left(\frac{\delta}{\delta(3+\delta)} \frac{1}{2} m_{j}\left|v_{j}-u\right|^{2}-\frac{2}{(3+\delta)} I_{j}^{2 / \delta_{j}}\right)_{j \in S} \\
=\left(\frac{1}{3} m_{j}\left|v_{j}-u\right|^{2}-\frac{2}{(3+\delta)}\left(m_{j} \frac{\left|v_{j}-u\right|^{2}}{2}+I_{j}^{2 / \delta_{j}}\right)\right)_{j \in S}  \tag{3.10}\\
\Psi^{\mathrm{tr}}=\left(\Psi_{j}^{t r}\right)_{j \in S}=\left(\frac{1}{2} m_{j}\left|v_{j}-u\right|^{2}\right)_{j \in S}  \tag{3.11}\\
\Psi^{\lambda}=\left(\Psi_{j}^{\lambda}\right)_{j \in S}=\left(\left(m_{j} \frac{\left(v_{j}-u\right)^{2}}{2}-\frac{5}{2} k_{B} T+I_{j}^{\frac{2}{\delta_{j}}}-k_{B} T \frac{\delta_{j}}{2}\right)\left(v_{j}-u\right)\right)_{j \in S} \tag{3.12}
\end{gather*}
$$

For any $j \in S$,

$$
\Psi^{\mathbf{D}_{\mathbf{j}}}=\left(\Psi_{i}^{D_{j}}\right)_{i \in S}=\frac{1}{p_{i}}\left(\delta_{i j}-\frac{\rho_{i}}{\rho}\right)\left(v_{i}-u\right), \quad i \in S,
$$

where $p_{i}=n_{i} k_{B} T$ represents the species partial pressure of the $i^{\text {th }}$ species.

### 3.2 Space of constraints

We define now the set constraints, in order to prescribe some properties to the BGK operator that we aim to construct. The principle is to garantee firstly the classical conservation properties (mass, total momentum, total energy). But also some supplementary moments have to be relaxed with a correct rate in order to recover correct transport coefficients. So, $\mathbf{f}$ being given, $K(\mathbf{f})$ is defined as the set of functions $\mathbf{g}=\left(g_{j}\right)_{j \in S}$ s.t. $g_{j} \geq 0$ for $j \in S$ and satisfying the constraints

$$
\begin{gather*}
\left\langle\left\langle\mathbf{g}-\mathbf{f}, \boldsymbol{\Psi}^{1}\right\rangle\right\rangle=0, \quad \mathbf{l} \in S \cup\{m m, e n\},  \tag{3.13}\\
\lambda\left\langle\left\langle\mathbf{g}-\mathbf{f}, \boldsymbol{\Psi}^{\mathbf{p r}}\right\rangle\right\rangle=-\lambda_{1}\left\langle\left\langle\mathbf{f}, \boldsymbol{\Psi}^{\mathbf{p r}}\right\rangle\right\rangle,  \tag{3.14}\\
\lambda\left\langle\left\langle\mathbf{g}-\mathbf{f}, \boldsymbol{\Psi}^{\mathbf{i n t}}\right\rangle\right\rangle=-\lambda_{2}\left\langle\left\langle\mathbf{f}, \boldsymbol{\Psi}^{\mathbf{i n t}}\right\rangle\right\rangle . \tag{3.15}
\end{gather*}
$$

The constraints (3.13) impose the conservation of mass, momentum and total energy for the resulting model. The relation (3.14) has been introduced in ([18]) for a single monoatomic gas and generalised next ([19], [16]). This constraint means more precisely that the solution of the homogeneous BGK model tends to an isotropic distribution function as time tends to infinity. The constraint (3.15) implies that the distribution function tends to a distribution function whose translational and internal macroscopic temperatures are equal. This relation has been introduced in ([19]). Hence the constraints $(3.14,3.15)$ are consistant with the fact that the distribution function tends to the Maxwellian (2.7, 2.8) when time tends to infinity.

In order to solve a entropy minimisation problem, the constraints (3.14, 3.15) should be recast in a more convenient form. So, by using (3.13, 3.11, 3.10), it comes that

$$
\left\langle\left\langle\mathbf{g}-\mathbf{f}, \Psi^{\mathbf{i n t}}\right\rangle\right\rangle=\frac{2}{3}\left\langle\left\langle\mathbf{g}-\mathbf{f}, \Psi^{\mathbf{t r}}\right\rangle\right\rangle
$$

So, the equation (3.15) can be rewritten as

$$
\frac{2}{3}\left\langle\left\langle\mathbf{g}, \boldsymbol{\Psi}^{\mathbf{t r}}\right\rangle\right\rangle=\frac{2}{3}\left(1-\frac{\lambda_{2}}{\lambda}\right)\left\langle\left\langle\mathbf{f}, \boldsymbol{\Psi}^{\mathbf{t r}}\right\rangle\right\rangle+\frac{\lambda_{2}}{\lambda} \frac{2}{3+\delta}\left\langle\left\langle\mathbf{f}, \boldsymbol{\Psi}^{\mathbf{e n}}\right\rangle\right\rangle .
$$

Hence by using the definition $e$ and $e_{\text {tr }}$ given in (2.2,2.1), the previous relation yields

$$
\begin{equation*}
\frac{2}{3}\left\langle\left\langle\mathbf{g}, \Psi^{\mathbf{t r}}\right\rangle\right\rangle=\frac{2}{3}\left(1-\frac{\lambda_{2}}{\lambda}\right) \rho e_{t r}+\frac{\lambda_{2}}{\lambda} \frac{2}{3+\delta} \rho e . \tag{3.16}
\end{equation*}
$$

But as $e=\frac{3+\delta}{2} k_{B} T_{e q}$ and $e_{t r}=\frac{3}{2} k_{B} T_{t r}$ and by setting $\theta=\frac{\lambda_{2}}{\lambda}$, the relation (3.16) reads

$$
\begin{equation*}
\left\langle\left\langle\mathbf{g}, \boldsymbol{\Psi}^{\mathbf{t r}}\right\rangle\right\rangle=\frac{3}{2}(1-\theta) \rho k_{B} T_{t r}+\frac{3}{2} \theta \rho k_{B} T_{e q} . \tag{3.17}
\end{equation*}
$$

From the definition (3.9) of $\Psi^{\mathbf{p r}}$, the relation (3.14) gives

$$
\sum_{i \in S} \int_{\mathbb{R}^{3} \times \mathcal{Q}_{i}} m_{i}\left(v_{i}-u\right) \otimes\left(v_{i}-u\right) g_{i} d v_{i} d I_{i}=\frac{2}{3}\left\langle\left\langle\mathbf{g}, \Psi^{\mathbf{t r}}\right\rangle\right\rangle I_{d}+\left(1-\frac{\lambda_{1}}{\lambda}\right)\left\langle\left\langle\mathbf{f}, \Psi^{\mathbf{p r}}\right\rangle\right\rangle .
$$

Moreover by setting

$$
\begin{equation*}
\frac{\lambda_{1}}{\lambda}=1-\nu(1-\theta) \tag{3.18}
\end{equation*}
$$

and by using the relation (3.17), we get

$$
\left\langle\left\langle\mathbf{g}, \boldsymbol{\Psi}^{\mathbf{p r}}\right\rangle\right\rangle=\left((1-\theta) \rho k_{B} T_{t r}+\theta \rho k_{B} T_{e q}\right) I_{d}+\nu(1-\theta)\left\langle\left\langle\mathbf{f}, \Psi^{\mathbf{t r}}\right\rangle\right\rangle .
$$

Hence by using the relation

$$
\left\langle\left\langle\mathbf{f}, \Psi^{\mathbf{p r}}\right\rangle\right\rangle=\rho \Theta,
$$

where $\Theta$ represents the pressure tensor, we get the relation

$$
\begin{equation*}
\left\langle\left\langle\mathbf{g}, \Psi^{\mathbf{p r}}\right\rangle\right\rangle=\rho \mathcal{T}, \tag{3.19}
\end{equation*}
$$

with

$$
\begin{equation*}
\mathcal{T}=(1-\theta)\left[(1-\nu) k_{B} T_{t r} I_{d}+\nu \Theta\right]+\theta k_{B} T_{e q} I_{d} . \tag{3.20}
\end{equation*}
$$

Hence, $K(\mathbf{f})$ is constituted by distribution functions $\mathbf{g}$ satisfying (3.13, 3.17, 3.19, 3.20). In the next steps of the paper, we will consider this version of $K(\mathbf{f})$.

### 3.3 Entropy minimisation problem

In this section we consider the variational problem
Find a solution to the minimisation problem

$$
\begin{equation*}
\mathbf{G}=\operatorname{argmin}_{\mathbf{g} \in K(\mathbf{f})} \mathcal{H}(\mathbf{g}), \tag{3.21}
\end{equation*}
$$

where $K(\mathbf{f})$ is the set of function $\mathbf{g}$ s.t $g_{i} \geq 0$ and s.t. the constraints $(3.13,3.17,3.19,3.20)$ are satisfied. We recall that $\mathcal{H}$ is the Boltzmann entropy defined in (2.6).

Theorem 3.1. Let $\mathbf{f}=\left(f_{j}\right)_{j \in S}$, be a nonnegative function, $\nu \in[-1 / 2,1[, \theta \in[0,1]$. Then the tensor $\mathcal{T}$ defined in (3.20) is symetric positive definite and the minimization problem (3.21) admits $a$ unique solution $\mathbf{G}=\left(G_{j}\right)_{j \in S}$, s.t.

$$
\begin{equation*}
G_{i}=\frac{n_{i}\left(k_{B} T\right)^{\left(3+\delta_{i}\right) / 2}}{\mathcal{Q}_{i}^{\text {tr }} \mathcal{Q}_{i}^{\text {int }} \sqrt{\operatorname{det}(\mathcal{T})}\left(k_{B} T_{\text {rel }}\right)^{\frac{\delta_{i}}{2}}} \exp \left(-\frac{m_{i}}{2}\left\langle\mathcal{T}^{-1}\left(v_{i}-u\right),\left(v_{i}-u\right)\right\rangle-\frac{I_{i}^{\frac{2}{\delta_{i}}}}{k_{B} T_{\text {rel }}}\right), i \in S \tag{3.22}
\end{equation*}
$$

where

$$
\begin{equation*}
T_{r e l}=\theta T_{e q}+(1-\theta) T_{i n t} . \tag{3.23}
\end{equation*}
$$

Proof. First of all, by arguing as in ([19]), we can show that $\mathcal{T} \in S_{3}^{+}(\mathbb{R})$ is equivalent to $\theta \in[0,1]$ and $\nu \in\left[-1 / 2,1\left[\right.\right.$. In ([3]) it is only proved that $\mathcal{T} \in S_{3}^{+}(\mathbb{R})$ implies that $\theta \in[0,1]$ and $\nu \in[-1 / 2,1[$. Moreover, in this proof, we follow the approach of Junk ([30]) that has been generalized to a mixture setting in ([28]). So, we proceed as in ([16], [17], [18], [19]). Let $v_{i, 1}, v_{i, 2}, v_{i, 3}$ be the three components of $v_{i}$. Hence, we consider the set

$$
\begin{array}{r}
\mathcal{L}=\left\{\left(\lambda_{l}\right)_{l \in S},\left(\alpha_{r}\right)_{r \in\{1, \ldots, 3\}},\left(\beta_{s}\right)_{s \in\{1, \ldots, 6\}}, \gamma, /\right. \\
\int_{\mathbb{R}^{3} \times \mathcal{Q}_{i}} \exp \left(\sum_{l \in S} \lambda_{l} \Psi_{i}^{l}+\sum_{r=1}^{3} \alpha_{r} v_{i, r}+\sum_{s=1}^{3} \beta_{s} v_{i, s}^{2}+\beta_{4} v_{i, 1} v_{i, 2}+\beta_{5} v_{i, 1} v_{i, 3}+\beta_{6} v_{i, 2} v_{i, 3}+\gamma I_{i}^{2 / \delta_{i}}\right) \\
\left.d v_{i} d I_{i}<+\infty\right\} .
\end{array}
$$

Let us show that $\mathcal{L}$ is open by proceeding as in $([16])$. Let $\left(\lambda_{l}\right)_{l \in S},\left(\alpha_{r}\right)_{r \in\{1, \ldots, 3\}},\left(\beta_{s}\right)_{s \in\{1, \ldots, 6\}}, \gamma \in$ $\mathcal{L}$. In that case, $\gamma<0$ and the signature of the quadratic form

$$
q\left(v_{i}\right)=\beta_{1} v_{i, 1}^{2}+\beta_{2} v_{i, 1}^{2}+\beta_{1} v_{i, 3}^{2}+\beta_{4} v_{i, 1} v_{i, 2}+\beta_{5} v_{i, 1} v_{i, 3}+\beta_{6} v_{i, 2} v_{i, 3}
$$

is $(0,3)$. Hence the Gauss reduction of the quadratic form writes

$$
q\left(v_{i}\right)=\beta_{1}\left(v_{i, 1}+\frac{\beta_{4}}{2 \beta_{1}} v_{i, 2}+\frac{\beta_{5}}{2 \beta_{1}} v_{i, 3}\right)^{2}+\alpha_{1}\left(v_{i, 2}+\frac{1}{2 \alpha}\left(\beta_{6}-\frac{\beta_{4} \beta_{5}}{2 \beta_{1}}\right) v_{i, 3}\right)^{2}+\alpha_{2} v_{i, 3}^{2},
$$

with $\beta_{1}<0, \alpha_{1}<0, \alpha_{2}<0$ where

$$
\alpha_{1}=\beta_{2}-\frac{\beta_{4}^{2}}{4 \beta_{1}} \quad \alpha_{2}=\beta_{2}-\frac{\beta_{5}^{2}}{4 \beta_{1}}+\frac{1}{4 \alpha}\left(\beta_{6}-\frac{\beta_{4} \beta_{5}}{2 \beta_{1}}\right) .
$$

Therefore by proceeding in the same way, we can prove that for $\varepsilon>0$ small enough, the signature of the quadratic form whose terms are $\beta_{j}+\varepsilon$ and $\beta_{j}-\varepsilon$ is still $(0,3)$. Moreover, $\varepsilon$ can be chosen such as $\gamma+\varepsilon<0$ and $\gamma-\varepsilon<0$. So $\mathcal{L}$ is open. Moreover, $\mathcal{L}$ is non empty.
Hence according to ([28], [30]), the solution $\mathbf{G}=\left(G_{i}\right)_{i \in s}$ of the minimisation problem (3.21) reads

$$
G_{i}=\alpha_{i} \exp \left(-m_{i}\left\langle v_{i}-u, \mathcal{A}\left(v_{i}-u\right)\right\rangle-a I^{\frac{2}{\delta_{i}}}\right), \quad i \in S,
$$

where $\mathcal{A} \in \mathcal{M}_{3}(\mathbb{R}), \alpha_{i} \in \mathbb{R}, a \in \mathbb{R}$. Next we aim to determine these parameters.
By using constraint (3.13), we get

$$
\begin{equation*}
\alpha_{i}=\operatorname{det}(\mathcal{A})^{1 / 2} n_{i} \frac{\left(k_{B} T\right)^{\left(3+\delta_{i}\right) / 2}}{\mathcal{Q}_{i}^{\text {tr }} \mathcal{Q}_{i}^{\text {int }}} a^{\delta_{i} / 2}, \quad i \in S . \tag{3.24}
\end{equation*}
$$

A straightforward computation gives

$$
\int_{\mathbb{R}^{3} \times \mathcal{Q}_{i}} m_{i}\left(v_{i}-u\right) \otimes\left(v_{i}-u\right) G_{i} d v_{i} d I_{i}=\alpha_{i} \frac{1}{2} \mathcal{A}^{-1} \frac{1}{a^{\frac{\delta_{i}}{2}}} \frac{\mathcal{Q}_{i}^{t r} \mathcal{Q}_{i}^{i n t}}{T^{\left(3+\delta_{i}\right) / 2}}=\frac{1}{2} n_{i} \mathcal{A}^{-1}
$$

Hence by comparing the two previous expressions with the relations (3.19, 3.20) we get $\mathcal{A}=\frac{1}{2} \mathcal{T}^{-1}$.
So (3.24) implies

$$
\alpha_{i}=\frac{n_{i}}{\mathcal{Q}_{i}^{\text {tr }} \mathcal{Q}_{i}^{\text {int }}} \frac{1}{\sqrt{\operatorname{det}(\mathcal{T})}}\left(k_{B} T\right)^{\left(3+\delta_{i}\right) / 2} a^{\delta_{i} / 2}, \quad i \in S
$$

By combining (3.13) and (3.16), it comes that

$$
\begin{equation*}
\frac{2}{3}\left(e-\sum_{i \in S} \alpha_{i} m_{i} \int_{\mathbb{R}^{3} \times \mathcal{Q}_{i}} I_{i}^{\frac{2}{\gamma_{i}}} \exp \left(-\frac{m_{i}}{2}\left\langle v-u, \mathcal{T}^{-1}(v-u)\right\rangle-a I^{\frac{2}{\delta_{i}}}\right) d v_{i} d I_{i}\right)=(1-\theta) \frac{2}{3} \rho e_{t r}+\theta \rho e . \tag{3.25}
\end{equation*}
$$

A straightforward computation gives that

$$
\left(\sum_{i \in S} \int_{\mathcal{Q}_{i}} I_{i}^{\frac{2}{\delta_{i}}} \exp \left(-a I_{i}^{\frac{2}{\delta_{i}}}\right) d I_{i}\right) a^{\frac{\delta_{i}}{2}} T^{\frac{\delta_{i}}{2}} \rho_{i} \frac{1}{\mathcal{Q}_{i}^{\text {int }}}=\frac{1}{a} \sum_{i \in S} \frac{\delta_{i}}{2} \rho_{i} .
$$

Hence the relation (3.25) gives

$$
\frac{2}{3}\left(e-\frac{1}{a} \sum_{i \in S} \frac{\delta_{i}}{2} \frac{\rho_{i}}{\rho}\right)=(1-\theta) \frac{2}{3} e_{t r}+\theta \frac{2}{3+\delta} e .
$$

So

$$
\frac{1}{a} \frac{\delta}{3}=\frac{2}{3} e-(1-\theta) \frac{2}{3} e_{t r}-\theta \frac{2}{3+\delta} e .
$$

By using that $e=e_{t r}+e_{i n t}$, we get

$$
\frac{1}{a} \frac{\delta}{3}=\left(\frac{2}{3}-\frac{2}{3+\delta}\right) \theta e+\frac{2}{3}(1-\theta) e_{i n t} .
$$

As $\frac{2}{3}-\frac{2}{3+\delta}=\frac{2 \delta}{3(3+\delta)}$, the previous relation gives $a=\frac{1}{k_{B} T_{r e l}}$ where $T_{\text {rel }}$ has been defined in (3.23) and we recover that $G_{i}$ is given by (3.22).

### 3.4 H theorem

Theorem 3.2. For all $-\frac{1}{2} \leq \nu<1$ and $\theta \in[0,1]$, we denote by $G_{i}^{\nu, \theta}$ the expression of $G_{i}$ given by (3.22) and by $\mathbf{G}^{\nu, \theta}$ the vector $\mathbf{G}^{\nu, \theta}=\left(G_{i}^{\nu, \theta}\right)_{i \in S}$. Hence, the entropy dissipation satisfies

$$
D(\mathbf{f})=\sum_{i \in S} \int_{\mathbb{R}^{3} \times \mathcal{Q}_{i}}\left(G_{i}^{\nu, \theta}-f_{i}\right) \ln \left(f_{i}\right) d v_{i} d I_{i} \leq 0
$$

Moreover $D(\mathbf{f}) \leq 0$ for $-\frac{1}{2} \leq \nu<1$ and $0 \leq \theta \leq 1$ with equality iff $\mathbf{f}=\mathcal{M}$, where $\mathcal{M}$ is given by (2.7).

Proof. By using the convexity of $x \ln (x)$, it holds that

$$
\left\langle\left\langle\mathbf{G}^{\nu, \theta}-\mathbf{f}, \ln (\mathbf{f})\right\rangle\right\rangle \leq \sum_{i \in S} \int_{\mathbb{R}^{3} \times \mathcal{Q}_{i}}\left(G_{i}^{\nu, \theta} \ln \left(G_{i}^{\nu, \theta}\right)-f_{i} \ln \left(f_{i}\right)\right) d v_{i} d I_{i} .
$$

By using the minimisation problem for $\nu=1$ and $\theta=0$, we get

$$
\sum_{i \in S} \int_{\mathbb{R}^{3} \times \mathcal{Q}_{i}} G_{i}^{1,0} \ln \left(G_{i}^{1,0}\right) d v_{i} d I_{i} \leq \mathcal{H}(\mathbf{f})
$$

where we have used for $G_{i}^{1,0}$ the previous notation. So

$$
\left\langle\left\langle\mathbf{G}^{\nu, \theta}-\mathbf{f}, \ln (\mathbf{f})\right\rangle\right\rangle \leq \sum_{i \in S} \int_{\mathbb{R}^{3} \times \mathcal{Q}_{i}}\left(G_{i}^{\nu, \theta} \ln \left(G_{i}^{\nu, \theta}\right)-G_{i}^{1,0} \ln \left(G_{i}^{1,0}\right)\right) d v_{i} d I_{i} .
$$

Moreover a straightforward computation gives ([3]),

$$
\begin{equation*}
\int_{\mathbb{R}^{3} \times \mathcal{Q}_{i}}\left(G_{i}^{\nu, \theta} \ln \left(G_{i}^{\nu, \theta}\right)-G_{i}^{\nu, \theta}\right) d v_{i} d I_{i}=\rho_{i} \ln \left(\frac{\rho_{i}}{\sqrt{(2 \pi \mathcal{T})}\left(k_{B} T_{r e l}\right)^{\frac{\delta_{i}}{2}}}\right)-\frac{3}{2} \rho_{i}, \quad i \in S \tag{3.26}
\end{equation*}
$$

we get

$$
\left\langle\left\langle\mathbf{G}^{\nu, \theta}-\mathbf{f}, \ln (\mathbf{f})\right\rangle\right\rangle \leq \frac{1}{2} \rho \ln \left(\frac{\operatorname{det}(\Theta)}{\operatorname{det}(\mathcal{T})} \frac{T_{i n t}^{\delta}}{T_{r e l}^{\delta}}\right) .
$$

The end of the proof is inspired fom ([18]). Consider $\lambda_{1}, \lambda_{2}, \lambda_{3}$ the eigenvalues of $\Theta$. Hence, we have to study the sign of

$$
\left.p(\nu, \theta)=\ln \left(\left(\prod_{i=1}^{3} \lambda_{i}\right) T_{\text {int }}^{\delta}\right)-\ln \left(\operatorname{det}\left((1-\theta)\left((1-\nu) T_{\text {tr }} I_{d}+\nu \Theta\right)+\theta T_{e q} I_{d}\right)\right) T_{\text {rel }}^{\delta}\right) .
$$

By using that $\operatorname{tr}(\Theta)=3 T_{t r}$, the maximum of $p$ is reached by $\lambda_{1}=\lambda_{2}=\lambda_{3}=T_{t r}$. Then, we have to study the sign of

$$
\begin{aligned}
\left.\ln \left(\left(T_{t r}\right)^{3} T_{\text {int }}^{\frac{\delta}{2}}\right)-\ln \left(\left((1-\theta) T_{t r}+\theta T_{e q} I_{d}\right)\right)^{3} T_{r e l}^{\delta}\right) & =3 \ln \left(T_{t r}\right)+\delta \ln \left(T_{\text {int }}\right) \\
& -3 \ln \left((1-\theta) T_{t r}+\theta T_{e q}\right)-\delta \ln \left(T_{\text {rel }}\right)
\end{aligned}
$$

Then, by using the concavity of $\ln$, we get

$$
\begin{array}{r}
3 \ln \left(T_{\text {tr }}\right)+\delta \ln \left(T_{\text {int }}\right)-3(1-\theta) \ln \left(T_{\text {tr }}\right)-3 \theta \ln \left(T_{\text {eq }}\right)-\delta \ln \left(T_{\text {rel }}\right) \\
\leq 3 \ln \left(T_{\text {tr }}\right)+\delta \ln \left(T_{\text {int }}\right)-3(1-\theta) \ln \left(T_{\text {tr }}\right)-3 \theta \ln \left(T_{\text {eq }}\right)-\delta \theta \ln \left(T_{\text {eq }}\right)-\delta(1-\theta) T_{\text {int }} .
\end{array}
$$

So,

$$
\begin{array}{r}
3 \ln \left(T_{\text {tr }}\right)+\delta \ln \left(T_{\text {int }}\right)-3(1-\theta) \ln \left(T_{\text {tr }}\right)-3 \theta \ln \left(T_{\text {eq }}\right)-\delta \ln \left(T_{\text {rel }}\right) \\
\leq 3 \theta \ln \left(T_{\text {tr }}\right)+\delta \theta \ln \left(T_{\text {int }}\right)-\theta(3+\delta) \ln \left(T_{\text {eq }}\right) .
\end{array}
$$

Therefore, by using the definition (2.4) of $T_{e q}$ and the concavity of $\ln$, we get that the right-hand side of the previous inequality is negative.

When $D(\mathbf{f})=0$, from previously we get $\Theta=T_{t r} I_{d}$. Moreover, we obtain $\mathcal{H}(\mathbf{f})=\mathcal{H}\left(\mathbf{G}^{\mathbf{1 , 0}}\right)$ and $\mathcal{H}(\mathbf{f})=\mathcal{H}\left(\mathbf{G}^{\nu, \theta}\right)$. By uniqueness of the minimisation problem, $\mathbf{f}$ is the Gaussian distribution satisfying $\mathbf{f}=\mathbf{G}^{\mathbf{1}, \mathbf{0}}$. Hence from (3.26), we get $T_{\text {int }}=T_{\text {rel }}$. So $T_{\text {int }}=T_{\text {tr }}=T_{\text {eq }}$. So $\mathbf{f}=\mathcal{M}$, where $\mathcal{M}$ is given by (2.7).

### 3.5 Indifferentiability principle

In this section, we show that our model satisfies the indiferentiability principle stated in ([2]) for an inert monoatomic gas mixture. This means that when all the molecular masses are equal, the distribution function that is obtained by adding all the species satisfies the single gas version of the present BGK model. In this paper, we aim to compare the present model with the single gas BGK models ([18], [19]).
If $S=S_{m}$, we consider a monoatomic mixture and we recover the model of ([16]). Therefore the distribution function $\mathbf{f}=\sum_{i \in S_{m}} f_{i}$ is solution of the Ellipsoidal Statistical Model for monospecies ([3], [18]).
In the case, where the mixture is purely polyatomic $\left(S=S_{p}\right)$, the distribution function $\mathbf{f}=\sum_{i \in S_{p}} f_{i}$ is solution of the polyatomic Ellipsoidal Statistical Model for monospecies ([3], [19]) when all the molecular masses are equal.

## 4 Chapman-Enskog expansion

This section is devoted to the derivation of the Navier-Stokes system starting from the ESBGK model obtained in Theorem 3.1. More precisely, we consider the system

$$
\begin{equation*}
\partial_{t} f_{i}+v \cdot \nabla_{x} f_{i}=\frac{\lambda}{\tau}\left(G_{i}-f_{i}\right), \quad i \in S, \tag{4.27}
\end{equation*}
$$

where $\tau$ is proportional to the Knudsen number. In this process, the relaxation coefficients $\lambda, \lambda_{1}$ and $\lambda_{2}$ are adjusted in order to fit the shear viscosity, the volume viscosity and the heat conductivity coefficient.

### 4.1 Euler system

Starting from (4.27), we can derive the compressible Euler system as in ([21]). Hence, we get

$$
\begin{gathered}
\partial_{t} \rho_{i}+\nabla \cdot\left(\rho_{i} u\right)=0, \quad i \in S, \\
\partial_{t}(\rho u)+\nabla_{x} \cdot\left(\rho u \otimes u+p I_{d}\right)=0, \\
\partial_{t}\left(\frac{1}{2} \rho u^{2}+\mathcal{E}\right)+\nabla_{x} \cdot\left(u\left(\frac{1}{2} \rho u^{2}+\mathcal{E}+p\right)\right)=0,
\end{gathered}
$$

where the internal energy $\mathcal{E}$ per unit volutme is defined by

$$
\mathcal{E}=n k_{B}\left(\frac{3}{2}+\frac{\delta}{2}\right)
$$

and $p=n k_{B} T$ represents the thermodynamic pressure.
The non conservative form of the Euler system writes

$$
\partial_{t} n_{i}+(u \cdot \nabla) n_{i}+n_{i} \nabla \cdot u=0, \quad i \in S,
$$

$$
\begin{gathered}
\partial_{t} u+u \cdot \nabla u+\frac{\nabla p}{\rho}=0, \\
\partial_{t} T+2 \frac{\sum_{i \in S} n_{i}}{3 \sum_{i \in S} n_{i}+\sum_{i \in S} \delta_{i} n_{i}} T \nabla \cdot u+u \cdot \nabla T=0 .
\end{gathered}
$$

### 4.2 Derivation of the Navier-Stokes Fourier system

### 4.2.1 Computation of the expansion

$\mathbf{f}=\left(f_{i}\right)_{i \in S}$ is expanded around a Maxwellian $\mathcal{M}=\left(\mathcal{M}_{i}\right)_{i \in S}$ as

$$
\begin{equation*}
f_{i}=\mathcal{M}_{i}+\tau \mathcal{M}_{i} f_{i}^{1}+\mathcal{O}\left(\tau^{2}\right) \tag{4.28}
\end{equation*}
$$

with

$$
\begin{equation*}
\left\langle\left\langle\mathcal{M} \mathbf{f}^{1}, \mathbf{\Psi}^{\mathbf{1}}\right\rangle\right\rangle=0, \quad l \in S \cup\{\mathbf{m m}, \mathbf{e n}\} . \tag{4.29}
\end{equation*}
$$

Moreover $G_{i}$ satisfies for any $i \in S$,

$$
\begin{equation*}
G_{i}=\mathcal{M}_{i}+\tau G_{i}^{1}+\mathcal{O}\left(\tau^{2}\right) \tag{4.30}
\end{equation*}
$$

with

$$
G_{i}^{1}=D G_{i}(\mathcal{M}) \cdot \mathcal{M} \mathbf{g}=\lim _{\tau \rightarrow 0} \frac{G_{i}(\mathcal{M}+\tau \mathcal{M} \mathbf{g})-\mathcal{M}_{i}}{\tau}
$$

Moreover, it can be proved that $\mathbf{G}^{\mathbf{1}}=\left(G_{i}^{1}\right)_{i \in S}$ satisfies

$$
\left\langle\left\langle\mathbf{G}^{\mathbf{1}}, \mathbf{\Psi}^{\mathbf{l}}\right\rangle\right\rangle=\mathcal{O}(\tau), \quad l \in S \cup\{\mathbf{m m}, \mathbf{e n}\} .
$$

Introduce (4.28) into (4.27) leads to

$$
\begin{equation*}
f_{i}^{1}=\frac{G_{i}^{1}}{\mathcal{M}_{i}}-\frac{1}{\lambda}\left(\partial_{t} \mathcal{M}_{i}+v \cdot \nabla_{x} \mathcal{M}_{i}\right) \frac{1}{\mathcal{M}_{i}}+\mathcal{O}(\tau) \tag{4.31}
\end{equation*}
$$

A direct computation gives

$$
\begin{align*}
\frac{1}{\mathcal{M}_{i}}\left(\partial_{t} \mathcal{M}_{i}+v \cdot \nabla_{x} \mathcal{M}_{i}\right) & =\sum_{j \in S} \Psi_{i}^{D_{j}} \cdot \nabla p_{j}+\frac{1}{k_{B} T} \Psi_{i}^{p r}: \nabla_{x} u+\Psi_{i}^{\lambda} \cdot \frac{\nabla T}{k_{B} T^{2}} \\
& +\left(\frac{2}{k_{B} T} \Lambda\left(\frac{\delta_{i}}{2} k_{B} T-I_{i}^{\frac{2}{\delta_{i}}}\right)+\frac{2}{k_{B} T}\left(\frac{1}{3}-\Lambda\right)\left(m_{i} \frac{\left(v_{i}-u\right)^{2}}{2}-\frac{3}{2} k_{B} T\right)\right) \nabla \cdot u \tag{4.32}
\end{align*}
$$

with

$$
\Lambda=\frac{\sum_{j \in S} n_{j}}{3 \sum_{j \in S} n_{j}+\sum_{j \in S} n_{j} \delta_{j}} .
$$

Finally, by using (4.32) $\mathbf{f}^{\mathbf{1}}=\left(f_{i}^{(1)}\right)_{i \in S}$ defined by (4.31) reads for $i \in S$

$$
\begin{align*}
f_{i}^{(1)} & =\frac{G_{i}^{1}}{\mathcal{M}_{i}}-\frac{1}{\lambda}\left(\sum_{j \in S} \Psi_{i}^{D_{j}} \cdot \nabla p_{j}-\frac{1}{k_{B} T} \Psi_{i}^{p r}: \nabla_{x} u-\Psi_{i}^{\lambda} \cdot \frac{\nabla T}{k_{B} T^{2}}\right) \\
& -\left(2 \frac{\Lambda}{k_{B} T}\left(k_{B} T \frac{\delta_{i}}{2}-I_{i}^{\frac{2}{\delta_{i}}}\right)+\frac{2}{k_{B} T}\left(\frac{1}{3}-\Lambda\right)\left(m_{i} \frac{\left(v_{i}-u\right)^{2}}{2}-\frac{3}{2} k_{B} T\right)\right) \nabla \cdot u . \tag{4.33}
\end{align*}
$$

### 4.2.2 Macroscopic equations and computation of the fluxes

In this section, the fluxes are computed and the relaxation parameters $\lambda, \lambda_{1}$ and $\lambda_{2}$ are fixed during the procedure.

By performing a Chapman-Engskog expansion we get

$$
\begin{aligned}
& \partial \rho_{i}+\nabla \cdot\left(\rho_{i} u\right)+\nabla \cdot \mathbf{D}^{(\mathbf{i})}=0, \\
& \partial_{t}(\rho u)+\nabla \cdot\left(\rho u \otimes u+p I_{d}\right)+\nabla \cdot \boldsymbol{\Pi}=0, \\
& \partial_{t}\left(\rho \frac{u^{2}}{2}+\mathcal{E}\right)+\nabla \cdot\left(\left(\rho \frac{u^{2}}{2}+\mathcal{E}+p\right) u\right)+\nabla \cdot \mathcal{Q}=0,
\end{aligned}
$$

where we have introduced the diffusion fluxes

$$
\mathbf{D}^{(\mathbf{i})}=\int_{\mathbb{R}^{3} \times \mathcal{Q}_{i}} \mathcal{M}_{i} f_{i}^{(1)} m_{i} v_{i} d v_{i} d I_{i}, i \in S,
$$

where we have introduced the the pressure tensor

$$
\boldsymbol{\Pi}=\sum_{i \in S} \int_{\mathbb{R}^{3} \times \mathcal{Q}_{i}} m_{i} v_{i} \otimes v_{i} \mathcal{M}_{i} f_{i}^{(1)} d v_{i} d I_{i}
$$

the heat flux $\mathcal{Q}$

$$
\mathcal{Q}=\sum_{i \in S} \int_{\mathbb{R}^{3} \times \mathcal{Q}_{i}}\left(m_{i} \frac{v_{i}^{2}}{2}+I_{i}^{\frac{2}{\gamma_{i}}}\right) v_{i} \mathcal{M}_{i} f_{i}^{(1)} d v_{i} d I_{i}
$$

As in $([26])$, the diffusion velocity can be introduced as $\mathcal{V}_{\mathbf{i}}=\frac{\mathrm{D}^{(\mathrm{i})}}{\rho_{i}}$. Hence using the expression (4.33) of $f_{i}^{(1)}$ and according to eveness properties

$$
\begin{aligned}
\mathbf{D}^{(\mathbf{i})} & =-\frac{\sqrt{k_{B} T}}{\lambda} \sum_{j \in S} \int_{\mathbb{R}^{3} \times \mathcal{Q}_{i}} \frac{n_{i}}{\mathcal{Q}_{i}^{t r} \mathcal{Q}_{i}^{t r}} \exp \left(-m_{i} \frac{\left(v_{i}-u\right)^{2}+2 I_{i}^{2 / \delta_{i}}}{2 k_{B} T}\right) \Psi_{i}^{D_{j}} \cdot \nabla p_{j} m_{i}\left(v_{i}-u\right) d v_{i} d I_{i} \\
& -\frac{1}{3} \int_{\mathbb{R}^{3} \times \mathcal{Q}_{i}} m_{i} \frac{n_{i}}{\mathcal{Q}_{i}^{t r} \mathcal{Q}_{i}^{t t}} \exp \left(-\frac{m_{i}(v-u)^{2}+2 I_{i}^{2 / \delta_{i}}}{2 k_{B} T}\right)\left(v_{i}-u\right) \Psi_{i}^{\lambda} \cdot \frac{\nabla T}{k_{B} T^{2}} d v_{i} d I_{i} .
\end{aligned}
$$

Moreover a direct computation gives

$$
-\frac{1}{3} \int_{\mathbb{R}^{3}} m_{i} \frac{n_{i}}{\mathcal{Q}_{i}^{t r}} \exp \left(-m_{i} \frac{(v-u)^{2}}{2 k_{B} T}\right)\left(m_{i} \frac{\left(v_{i}-u\right)^{2}}{2}-\frac{5}{2} k_{B} T\right)\left(v_{i}-u\right)^{2} d v_{i}=-\frac{n_{i}}{3}\left(\frac{15}{2}-\frac{15}{2}\right)=0 .
$$

So, $\mathbf{D}^{(\mathbf{i})}$ writes

$$
\mathbf{D}^{(\mathbf{i})}=-\frac{\sqrt{k_{B} T}}{\lambda p_{i}} \sum_{j \in S} \int_{\mathbb{R}^{3} \times \mathcal{Q}_{i}} m_{i} \frac{n_{i}}{\mathcal{Q}_{i}^{t r}} \exp \left(-m_{i} \frac{\left(v_{i}-u\right)^{2}}{2 T}\right)\left(\delta_{i j}-\frac{m_{j} n_{i}}{\rho}\right)\left(v_{i}-u\right)^{2} d v_{i} d I_{i} \nabla p_{j} .
$$

So

$$
\begin{equation*}
\mathbf{D}^{(\mathbf{i})}=-\frac{\sqrt{k_{B} T}}{\lambda} n \sum_{j \in S}\left(\delta_{i j}-\frac{m_{j} n_{i}}{\rho}\right) \frac{\nabla p_{j}}{p} . \tag{4.34}
\end{equation*}
$$

Then by comparison with [26], the species multicomponent diffusion coefficient $D_{i j}$ for $i, j \in S$ reads

$$
D_{i j}=\frac{\sqrt{k_{B} T} n}{\lambda} \sum_{j \in S}\left(\delta_{i j}-\frac{m_{j} n_{i}}{\rho}\right),
$$

where $\lambda$ will be fixed during the computation of $\kappa$.
Moreover, according to (4.34), the model gives a Soret effect that is equal to 0 . Indeed, we can show that

$$
\begin{equation*}
\left\langle\left\langle\mathbf{\Psi}^{\mathbf{D}_{\mathbf{i}}}, \mathcal{M} \mathbf{f}^{\mathbf{1}}\right\rangle\right\rangle=\frac{1}{\rho_{i}} \mathbf{D}^{(\mathbf{i})} . \tag{4.35}
\end{equation*}
$$

More precisely, formula (4.35) is obtained by developping $\left\langle\left\langle\boldsymbol{\Psi}^{\mathrm{D}_{\mathbf{i}}}, \mathcal{M} \mathbf{f}^{\mathbf{1}}\right\rangle\right\rangle$ as

$$
\left\langle\left\langle\mathbf{\Psi}^{\mathbf{D}_{\mathbf{i}}}, \mathcal{M} \mathbf{f}^{\mathbf{1}}\right\rangle\right\rangle=\sum_{j \in S} \int_{\mathbb{R}^{3} \times \mathcal{Q}_{j}} \frac{1}{p_{j}}\left(\delta_{i j}-\frac{\rho_{j}}{\rho}\right)\left(v_{j}-u\right) \mathcal{M}_{j} f_{j}^{(1)} d v_{j} d I_{j} .
$$

So by using the orthogonality relation for the momentum (4.29), we get (4.35). Therefore,

$$
\frac{1}{\rho_{i}} \mathbf{D}^{(\mathbf{i})}=\mathcal{V}_{i}=\sum_{j \in S} D_{i j} \frac{\nabla p_{j}}{p}-\theta_{i} \frac{\nabla T}{T},
$$

with

$$
\theta_{i}=\frac{1}{3}\left\langle\left\langle\boldsymbol{\Psi}^{\mathbf{D}_{\mathbf{i}}}, \boldsymbol{\Psi}^{\lambda} \mathcal{M}\right\rangle\right\rangle .
$$

$\theta_{i}$ represents the thermal diffusion coeffcient ([26]) and yields 0 in the present case. This term correspond to the Soret effect.
Next, by using the constraint (3.15) and the expansions (4.28, 4.30), it holds that

$$
\sum_{i \in S} \int_{\mathbb{R}^{3} \times \mathcal{Q}_{i}} m_{i}(v-u)^{2} \lambda\left(G_{i}^{1}-\mathcal{M}_{i} f_{i}^{(1)}\right) d v_{i}=-\lambda_{2} \sum_{i \in S} \int_{\mathbb{R}^{3} \times \mathcal{Q}_{i}} m_{i}\left(v_{i}-u\right)^{2} \mathcal{M}_{i} f_{i}^{(1)} d v_{i} d I_{i} .
$$

Moreover by using (4.31), it comes that

$$
-\lambda_{2} \sum_{i \in S} \int_{\mathbb{R}^{3} \times \mathcal{Q}_{i}} m_{i}\left(v_{i}-u\right)^{2} \mathcal{M}_{i} f_{i}^{(1)} d v_{i} d I_{i}=\sum_{i \in S} \int_{\mathbb{R}^{3} \times \mathcal{Q}_{i}}\left(\partial_{t} \mathcal{M}_{i}+v \cdot \nabla \mathcal{M}_{i}\right) m_{i}\left(v_{i}-u\right)^{2} d v_{i} d I_{i} .
$$

Hence from (4.32), it holds that

$$
\begin{array}{r}
-\lambda_{2} \sum_{i \in S} \int_{\mathbb{R}^{3} \times \mathcal{Q}_{i}} m_{i}\left(v_{i}-u\right)^{2} \mathcal{M}_{i} f_{i}^{(1)} d v_{i} d I_{i} \\
=-\sum_{i \in S} \int_{\mathbb{R}^{3} \times \mathcal{Q}_{i}} m_{i}\left(v_{i}-u\right)^{2}\left(2 \Lambda\left(\frac{\delta_{i}}{2}-\frac{I^{\frac{2}{\delta_{i}}}}{k_{B} T}\right)+2\left(\frac{1}{3}-\Lambda\right)\left(m_{i} \frac{\left(v_{i}-u\right)^{2}}{2 k_{B} T}-\frac{3}{2}\right)\right) \mathcal{M}_{i} d v_{i} d I_{i} \nabla \cdot u
\end{array}
$$

A straightforward computation gives

$$
\int_{\mathbb{R}^{3} \times \mathcal{Q}_{i}} m_{i}\left(v_{i}-u\right)^{2}\left(\frac{\delta_{i}}{2}-\frac{I^{\frac{2}{\delta_{i}}}}{k_{B} T}\right) \mathcal{M}_{i} d v_{i} d I_{i}=0,
$$

and

$$
\sum_{i \in S} \int_{\mathbb{R}^{3} \times \mathcal{Q}_{i}} m_{i} \frac{\left(v_{i}-u\right)^{2}}{T}\left(m_{i} \frac{\left(v_{i}-u\right)^{2}}{2 k_{B} T}-\frac{3}{2}\right) \mathcal{M}_{i} d v_{i} d I_{i}=3 \sum_{i \in S} n_{i} .
$$

So

$$
-\lambda_{2} \sum_{i \in S} \int_{\mathbb{R}^{3} \times \mathcal{Q}_{i}} m_{i}\left(v_{i}-u\right)^{2} \mathcal{M}_{i} f_{i}^{(1)} d v_{i} d I_{i}=-6 k_{B} T \sum_{i \in S} n_{i}\left(\frac{1}{3}-\Lambda\right) \nabla \cdot u .
$$

Then by comparing with the viscous stress tensor, it holds that the second viscosity $\eta$ satisfies

$$
\eta=\frac{2}{\lambda_{2}} k_{B} T \sum_{i \in S} n_{i}\left(\frac{1}{3}-\Lambda\right)=\frac{2 n k_{B} T}{\lambda_{2}}\left(\frac{1}{3}-\Lambda\right)
$$

and can be adjusted from $\lambda_{2}$. Due to orthogonality relations (4.29), $\boldsymbol{\Pi}$ reads

$$
\boldsymbol{\Pi}=\sum_{i \in S} \int_{\mathbb{R}^{3} \times \mathcal{Q}_{i}} m_{i}\left(v_{i}-u\right) \otimes\left(v_{i}-u\right) \mathcal{M}_{i} f_{i}^{(1)} d v_{i} d I_{i}
$$

Next, we insert the expansion (4.28) into the constraint (3.14). So

$$
\left\langle\left\langle\mathbf{\Psi}^{\mathrm{pr}}, \mathbf{G}^{1}-\mathcal{M} \mathbf{f}^{(1)}\right\rangle\right\rangle=-\lambda_{1}\left\langle\left\langle\Psi^{\mathrm{pr}}, \mathcal{M} \mathbf{f}^{(1)}\right\rangle\right\rangle .
$$

Hence by using the relation (4.33) together with orthogonality relations, it comes that

$$
\left\langle\left\langle\Psi^{\mathrm{pr}}, \mathcal{M} \mathbf{f}^{(1)}\right\rangle\right\rangle=-\frac{1}{\lambda_{1}} \sum_{i \in S} \int_{\mathbb{R}^{3} \times \mathcal{Q}_{i}} \Psi_{i}^{p r}: \Psi_{i}^{p r} \mathcal{M}_{i} d v_{i} d I_{i} \frac{1}{2}\left(\nabla u+\nabla u^{t}-\frac{2}{3} \nabla \cdot u\right) .
$$

So

$$
\left\langle\left\langle\Psi^{\mathrm{pr}}, \mathcal{M} \mathbf{f}^{(1)}\right\rangle\right\rangle=-\frac{n k_{B} T}{\lambda_{1}} \frac{1}{2}\left(\nabla u+\nabla u^{t}-\frac{2}{3} \nabla \cdot u I_{d}\right) .
$$

Then the viscosity $\mu$, satisfies $\mu=\frac{n k_{B} T}{\lambda_{1}}$ and can be adjusted from $\lambda_{1}$.
Next, the heat flux writes

$$
\mathcal{Q}=\boldsymbol{\Pi} u+\sum_{i \in S} \int_{\mathbb{R}^{3} \times \mathcal{Q}_{i}}\left(m_{i} \frac{\left(v_{i}-u\right)^{2}}{2}+I_{i}^{\frac{2}{\delta_{i}}}\right)\left(v_{i}-u\right) \mathcal{M}_{i} f_{i}^{(1)} d v_{i} d I_{i} .
$$

Therefore, it comes that

$$
\mathcal{Q}=\boldsymbol{\Pi} u+\left\langle\left\langle\mathbf{\Psi}^{\lambda}, \mathcal{M} \mathbf{f}^{(\mathbf{1})}\right\rangle\right\rangle+\sum_{i \in S} k_{B} T \int_{\mathbb{R}^{3} \times \mathcal{Q}_{i}} \mathcal{M}_{i} f_{i}^{(1)}\left(\frac{5}{2}+\frac{\delta_{i}}{2}\right)\left(v_{i}-u\right) d v_{i} d I_{i}
$$

Hence by introducing the enthalpy $h_{i}=\left(\frac{5}{2} T+\frac{\delta_{i}}{2} T\right) \frac{k_{B}}{m_{i}}$ of $i^{\text {th }}$ species, with the convention that $\delta_{i}=0$ for $i \in S_{m}$, it holds that

$$
\mathcal{Q}=\mathbf{\Pi} u+\left\langle\left\langle\mathbf{\Psi}^{\lambda}, \mathcal{M} \mathbf{f}^{\mathbf{1}}\right\rangle\right\rangle+\sum_{i \in S} h_{i} \mathbf{D}^{(\mathbf{i})}
$$

By using the expression of $\mathcal{M}_{i} f_{i}^{(1)}$ together with orthogonality properties, it holds that

$$
\begin{aligned}
\mathcal{Q} & =\boldsymbol{\Pi} u-\frac{1}{\lambda} \sum_{i \in S} \int_{\mathbb{R}^{3} \times \mathcal{Q}_{i}} \sum_{j \in S}\left(\Psi_{i}^{D_{j}} \cdot \nabla p_{j}\right)\left(\frac{1}{2} m_{i}\left(v_{i}-u\right)^{2}-\frac{5}{2} k_{B} T+I_{i}^{\frac{2}{\delta_{i}}}-\frac{\delta_{i}}{2} k_{B} T\right)\left(v_{i}-u\right) \mathcal{M}_{i} d v_{i} d I_{i} \\
& -\frac{1}{3 \lambda}\left\langle\left\langle\Psi^{\lambda}, \mathcal{M} \Psi^{\lambda}\right\rangle\right\rangle \frac{\nabla T}{k_{B} T^{2}}+\sum_{i \in S} h_{i} \mathbf{D}^{(\mathbf{i})} .
\end{aligned}
$$

Moreover, a direct computation gives

$$
\left\langle\left\langle\Psi^{\lambda}, \mathcal{M} \Psi^{\lambda}\right\rangle\right\rangle=\left(k_{B} T\right)^{3} \sum_{i \in S}\left(\frac{5}{2}+\frac{\delta_{i}}{2}\right) \frac{n_{i}}{m_{i}}
$$

So, the expression of $\mathcal{Q}$ yields

$$
\mathcal{Q}=\boldsymbol{\Pi} u-\frac{k_{B}^{2} T}{\lambda} \sum_{i \in S}\left(\frac{5}{2}+\frac{\delta_{i}}{2}\right) \frac{n_{i}}{m_{i}} \nabla T+\sum_{i \in S} h_{i} \mathbf{D}^{(\mathbf{i})}-\frac{1}{3 \lambda} \sum_{j \in S}\left\langle\left\langle\mathbf{\Psi}^{\mathbf{D}_{\mathbf{j}}}, \boldsymbol{\Psi}^{\lambda} \mathcal{M}\right\rangle\right\rangle \nabla p_{j}
$$

But, as $\left\langle\left\langle\Psi^{\mathrm{D}_{\mathbf{j}}}, \Psi^{\lambda} \mathcal{M}\right\rangle\right\rangle=0, \mathcal{Q}$ writes finally

$$
\begin{equation*}
\mathcal{Q}=\Pi u-\frac{k_{B}^{2} T}{\lambda} \sum_{i \in S}\left(\frac{5}{2}+\frac{\delta_{i}}{2}\right) \frac{n_{i}}{m_{i}} \nabla T+\sum_{i \in S} h_{i} \mathbf{D}^{(\mathbf{i})} \tag{4.36}
\end{equation*}
$$

So

$$
\kappa=\frac{k_{B}^{2} T}{\lambda} \sum_{i \in S}\left(\frac{5}{2}+\frac{\delta_{i}}{2}\right) \frac{n_{i}}{m_{i}}
$$

Hence, the heat conductivity coefficient can be obtained from $\lambda$. Moreover, the relation (4.36) implies that the Duffour effect yields 0 which is consistent with the fact that the Soret effect is equal to 0 . This point comes from the fact that $\left\langle\left\langle\Psi^{\mathbf{D}_{\mathbf{j}}}, \Psi^{\lambda} \mathcal{M}\right\rangle\right\rangle=0$.

### 4.3 Comparison with the Ellipsoidal Statistical Model

According to (3.18), $\lambda$ satisfies the relation

$$
\lambda=\frac{\lambda_{1}}{(1-\nu+\theta \nu)}=\frac{n k_{B} T}{\mu(1-\nu+\theta \nu)}
$$

and the relaxation operator reads

$$
\frac{n k_{B} T}{\mu(1-\nu+\theta \nu)}\left(G_{i}-f_{i}\right), \quad i \in S
$$

Therefore, we obtain a generalisation of the Ellipsoidal Statistical Model for a mixture of any monoatomic components and any polyatomic components.

Define the mixture enthalpy $h$ by the relation ([26])

$$
h=\sum_{i \in S} \frac{\rho_{i}}{\rho} h_{i}=\frac{1}{\rho} \sum_{i \in S} n_{i} k_{B}\left(\frac{5}{2} T+\frac{\delta_{i}}{2} T\right) .
$$

Hence, the constant pressure specific heat $c_{p}$ reads ([1])

$$
\begin{equation*}
c_{p}=\frac{\partial}{\partial T} h=\sum_{i \in S} \frac{\rho_{i}}{\rho} h_{i}=\frac{1}{\rho} \sum_{i \in S} n_{i} k_{B}\left(\frac{5}{2}+\frac{\delta_{i}}{2}\right) . \tag{4.37}
\end{equation*}
$$

The Prandtl number can be defined by $\operatorname{Pr}=\frac{c_{p} \mu}{\kappa}$. So by using the definition of $\mu$, the definition (4.37) of $c_{p}$ and the definition of $\lambda$, we obtain

$$
\begin{equation*}
\operatorname{Pr}=\frac{n}{\rho} \frac{\lambda}{\lambda_{1}} \frac{\sum_{i \in S} n_{i}\left(\frac{5}{2}+\frac{\delta_{i}}{2}\right)}{\sum_{i \in S} \frac{n_{i}}{m_{i}}\left(\frac{5}{2}+\frac{\delta_{i}}{2}\right)}=\frac{n}{\rho} \frac{\sum_{i \in S} n_{i}\left(\frac{5}{2}+\frac{\delta_{i}}{2}\right)}{\sum_{i \in S} \frac{n_{i}}{m_{i}}\left(\frac{5}{2}+\frac{\delta_{i}}{2}\right)} \frac{1}{(1-\nu+\theta \nu)}, \tag{4.38}
\end{equation*}
$$

where $\theta \in[0,1]$ and $\nu \in\left[-\frac{1}{2}, 1[\right.$ is chosen according to Theorem 3.2.
We remark that in case of indifferentiability, when all the molecular masses are equal, the formula (4.38) reduces to

$$
\operatorname{Pr}=\frac{1}{(1-\nu+\theta \nu)}
$$

as in ([3], [18]). For some comparisons with values of Prandtl number, we refer to ([22]).

## 5 Conclusion

We have built up an Ellipsoidal Statistical Model for a mixture of any component of monoatomic and polyatomic gases, where the non-translational degrees of freedom are modeled by a continous variable. The construction is based on the resolution of an entropy minimisation problem under moments constraints and generalizes the papers ([18], [19], [17], [16]). The resulting model is made of a unique attractor and reproduces the correct equilibrium states of ([6]). Moreover, it is consistent with the correct conservation laws, recovers the H theorem and satisfies an indifferentiability principle. We have next developped a Chapman-Enskog expansion in the spirit of ([6]) and a NavierStokes system has been derived. The structure of the fluxes has been of course recovered. During the procedure, the free parameters have been fixed in order to fit the shear viscosity, the volume viscosity and the thermal heat conductivity.

As a perspective, we planned to design a BGK model for a mixture of any component of monoatomic and polyatomic gases in the spirit of ([17]) with a continous non-translational energy variable. Moreover, we aim to generalise this work to discrete energies by proceeding like in ([38]). The case of fitting the Fick matrix in the context of a mixture of monoatomic and polyatomic components for a continous energy variable is left in perspective.

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