

# Particle-In-Cell simulations for highly oscillatory Vlasov-Poisson system

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# Outline

- 1 General context
- 2 The time scheme
- 3 An efficient PIC implementation

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## 4d Vlasov-Poisson equation – strong magnetic field

For  $\varepsilon \rightarrow 0$  solve numerically in  $t_f \sim 1$  and  $t_f \sim 1/\varepsilon$

$$\left\{ \begin{array}{l} \partial_t f^\varepsilon + \mathbf{v} \cdot \nabla_{\mathbf{x}} f^\varepsilon + \left( \mathbf{E}^\varepsilon + \frac{1}{\varepsilon} \mathbf{v}^\perp \right) \cdot \nabla_{\mathbf{v}} f^\varepsilon = 0, \\ \mathbf{E}^\varepsilon(\mathbf{x}, t) = -\nabla_{\mathbf{x}} \phi^\varepsilon, \quad -\Delta_{\mathbf{x}} \phi^\varepsilon = \int_{\mathbb{R}^2} f^\varepsilon d\mathbf{v} - n_i, \\ f^\varepsilon(\mathbf{x}, \mathbf{v}, t = 0) = f_0(\mathbf{x}, \mathbf{v}), \end{array} \right.$$

where

- $f^\varepsilon = f^\varepsilon(t, \mathbf{x}, \mathbf{v})$  particles distribution function
- Position  $\mathbf{x} = (x_1, x_2)$ , Velocity  $\mathbf{v} = (v_1, v_2)$ , and  $\mathbf{v}^\perp = (-v_2, v_1)$
- **Strong** and constant magnetic field in the  $x_3$  direction
- $\mathbf{E}^\varepsilon(\mathbf{x}, t)$  evolves in the plane  $\perp$  to the magnetic field.

E. Frénod, E. Sonnendrücker, M3AS, 2000. Drift phenomenon on a long time scale due to the self-consistent electric field  $\perp$  to the strong magnetic field.

## 4d Vlasov-Poisson equation – strong magnetic field

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### Difficulties:

- nonlinear coupling
- high frequency oscillations induced by  $\frac{1}{\varepsilon}$ .
- $\varepsilon \sim 0$  but not uniformly.

## Existing methods for similar problems

- reduce the dimensionality, by decoupling slow and fast dynamics and finding an invariant: Littlejohn (1979), Hahm (1988), Brizard (1995) etc. Frénod, Lutz (2014), Lutz (2014)
- homogenization – the two-scale limit (Frénod, Sonnendrücker 1998, 2001, 2009) :  $f^\varepsilon \rightarrow F$  when  $\varepsilon \rightarrow 0$ .  
The limit solves an equation free of oscillations.
- micro/macro decomposition (identify the limit model + reformulation):
  - double scale reformulation of the equation (Crouseilles-Lemou-Méhats, 2013)
  - Two-Scale-Asymptotic-Preserving-Schemes (Frénod-Crouseilles-H.-Mouton, 2011)

# Particle-In-Cell method

- The unknown is approximated by a collection of **macroparticles**  $(\mathbf{X}_k(t), \mathbf{V}_k(t))$

$$f_{N_p}^\varepsilon(t, \mathbf{x}, \mathbf{v}) = \sum_{k=1}^{N_p} \omega_k \delta(\mathbf{x} - \mathbf{X}_k(t)) \delta(\mathbf{v} - \mathbf{V}_k(t))$$

which move along the characteristic curve of Vlasov equation:

$$\begin{cases} \mathbf{X}'(t) = \mathbf{V}(t), \\ \mathbf{V}'(t) = \frac{1}{\varepsilon} \mathbf{V}^\perp(t) + \mathbf{E}^\varepsilon(t, \mathbf{X}(t)), \end{cases}$$

- Random initial particles.
  - deposit particles on the grid  $\Rightarrow$  the grid density (the RHS of Poisson equation).
  - solve Poisson equation on the grid  $\Rightarrow$  the grid electric field  $\mathbf{E}$ .
  - interpolate  $\mathbf{E}$  in each particle.
  - push particles with this field.

# Highly oscillatory solutions

- When  $\mathbf{E} \equiv 0$ , the solution is

$$\mathbf{X}(t) = \mathbf{x}_0 + \varepsilon \mathbf{v}_0^\perp - \varepsilon \mathcal{R}\left(\frac{t}{\varepsilon}\right) \mathbf{v}_0^\perp$$

$$\mathbf{V}(t) = \mathcal{R}\left(\frac{t}{\varepsilon}\right) \mathbf{v}_0$$

where  $\mathcal{R}(\tau) = \begin{pmatrix} \cos \tau & \sin \tau \\ -\sin \tau & \cos \tau \end{pmatrix}$  and  $\mathbf{x}_0 + \varepsilon \mathbf{v}_0^\perp$  is the **guiding center**.

- When the electric field  $\mathbf{E}$  is not zero  $\Rightarrow$  **stiff** solutions (evolving on two disparate time scales)



## General problem

Solve numerically **stiff** ODEs where stiffness arises from the **linear** term

$$y'(t) = \frac{1}{\varepsilon}Ly(t) + F(t, y(t)).$$

### Aim:

- perform **long-time** simulation of the ODE with large time steps with respect to the oscillation.
- the numerical scheme needs to **work uniformly** when  $\varepsilon \rightarrow 0$ .
- the numerical scheme needs to be stable and accurate for **any** initial condition.

The solution is

$$y_{n+1} = e^{(\Delta t/\varepsilon)L}y_n + e^{(\Delta t/\varepsilon)L} \int_{t_n}^{t_{n+1}} e^{(t_n-\tau)/\varepsilon L} F(\tau, y(\tau)) d\tau.$$

- the stiff part is solved **exactly**.
- **Q.:** How to derive approximations to the integral term?

M. Hochbruck, A. Ostermann, *Exponential integrators*, 2010.

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# Back to the PIC scheme for the Vlasov-Poisson system

$$\begin{aligned} \mathbf{X}'(t) &= \mathbf{V}(t), & \mathbf{X}(0) &= \mathbf{x}_0 \\ \mathbf{V}'(t) &= \frac{1}{\varepsilon} \mathbf{V}^\perp(t) + \mathbf{E}^\varepsilon(t, \mathbf{X}(t)), & \mathbf{V}(0) &= \mathbf{v}_0 \end{aligned}$$

where  $\mathbf{E}^\varepsilon$  is either given or computed by the Poisson equation.

The **exponential integrator** in **velocity**:

- $\mathbf{V}(t) = e^{\frac{t-s}{\varepsilon}L} \mathbf{V}(s) + e^{\frac{t-s}{\varepsilon}L} \int_s^t e^{\frac{s-\tau}{\varepsilon}L} \mathbf{E}^\varepsilon(\mathbf{X}(\tau), \tau) d\tau.$
- $\mathbf{X}(t) = \mathbf{X}(s) + \int_s^t \mathbf{V}(\tau) d\tau.$

where

$$L = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}, \quad \text{and} \quad e^{\tau L} = \mathcal{R}(\tau)$$

# The new time-stepping scheme

We want  $\Delta t \gg \varepsilon$ . Find the integer  $N$  and the real  $o$  s.t.

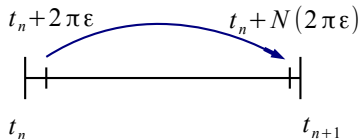
$$\Delta t = N \cdot (2\pi\varepsilon) + o$$

We approximate the integral term by

$$\int_{t_n}^{t_n + N(2\pi\varepsilon)} \mathcal{R}\left(\frac{t_n - \tau}{\varepsilon}\right) \mathbf{E}^\varepsilon(\mathbf{X}(\tau), \tau) d\tau \simeq N \cdot \int_{t_n}^{t_n + 2\pi\varepsilon} \dots d\tau$$

**Assumption:**  $\tau \rightarrow \mathbf{E}^\varepsilon(\mathbf{X}(\tau), \tau) \simeq 2\pi\varepsilon$ -periodic.

$$\begin{pmatrix} \mathbf{X}(t_n + N \cdot 2\pi\varepsilon) \\ \mathbf{V}(t_n + N \cdot 2\pi\varepsilon) \end{pmatrix} = \begin{pmatrix} \mathbf{X}_n \\ \mathbf{V}_n \end{pmatrix} + N \begin{pmatrix} \mathbf{X}(t_n + 2\pi\varepsilon) - \mathbf{X}_n \\ \mathbf{V}(t_n + 2\pi\varepsilon) - \mathbf{V}_n \end{pmatrix}.$$

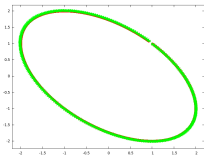


# First test-case: 4d linear Vlasov equation

Verification in a linear case:

$$\mathbf{E}^\varepsilon(\mathbf{x}, t) = \begin{pmatrix} 2x_1 + x_2 \\ x_1 + 2x_2 \end{pmatrix}$$

- identify the **slow motion**  $\sim \sin(\sqrt{3}\varepsilon t)$  and **fast motion**  $\sim \cos(t/\varepsilon)$



$\varepsilon = 0.01$ ,  $(1, 1, 1, 1)$  initial condition **far** from the slow manifold, final time  $t = 360$ .

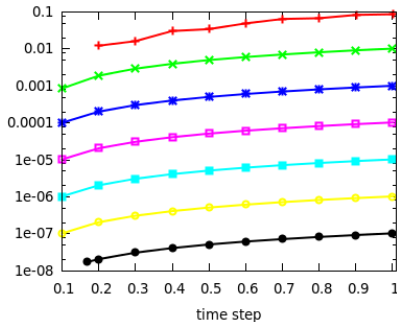
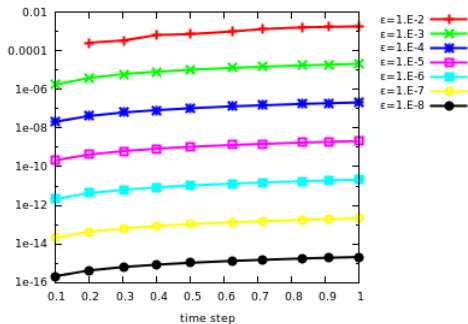
- tests with initial conditions close to/far from the slow manifold (that particular solution (or i.c.) for which the fast oscillations disappear.)
- **global errors** at short time ( $t = 10$ ) and long time ( $t = 1/\varepsilon$ )

# 4d linear Vlasov equation: global errors

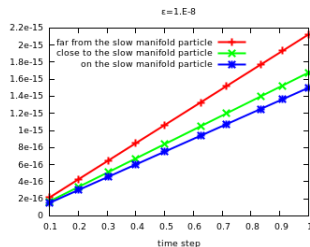
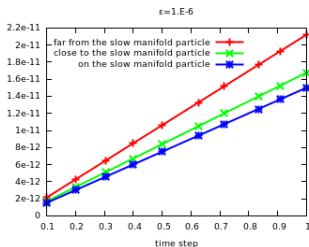
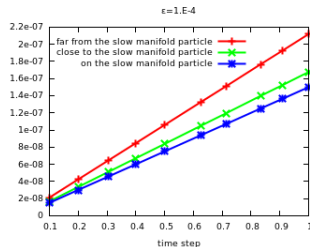
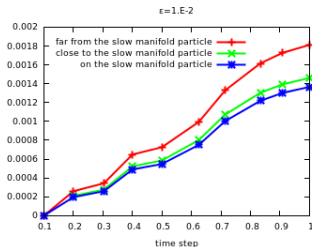
	$\Delta t = 1E-1$	$\Delta t = 2E-1$	$\Delta t = 5E-1$	$\Delta t = 8E-1$	$\Delta t = 1$
$\varepsilon = 1.E-2$	1	3	7	12	15
$\varepsilon = 1.E-4$	159	318	795	1273	1591
$\varepsilon = 1.E-6$	15915	31830	79577	127323	159154

**Table:** The whole number of rapid full tours enclosed in a time step of the scheme

uniformly accurate when  $\varepsilon$  vanishes



# Global errors at final time 10: $\varepsilon = 10^{-2}, 10^{-4}, 10^{-6}, 10^{-8}$



- the same order of error for different initial conditions.
- similar behaviour at long times ( $\sim 1/\varepsilon$ ).



## Second test-case: the Vlasov-Poisson system

- 1 Compare in **short** time ( $t \sim 1$ )

$$\partial_t f^\varepsilon + \mathbf{v} \cdot \nabla_x f^\varepsilon + \left( \mathcal{E}^\varepsilon + \frac{1}{\varepsilon} \mathbf{v}^\perp \right) \cdot \nabla_v f^\varepsilon = 0 \quad + \text{Poisson}$$

and the reduced model

$$\partial_t f_{GC} + \varepsilon \mathbf{E}^\perp \cdot \nabla_x f_{GC} = 0 \quad + \text{Poisson.}$$

- 2 Compare in **long** time ( $t \sim 1$ )

$$\partial_t g^\varepsilon + \frac{1}{\varepsilon} \left( \mathbf{v} \cdot \nabla_x g^\varepsilon + \left( \mathcal{E}^\varepsilon + \frac{1}{\varepsilon} \mathbf{v}^\perp \right) \cdot \nabla_v g^\varepsilon \right) = 0 \quad + \text{Poisson}$$

and the limit model

$$\partial_t g_{GC} + \mathbf{E}^\perp \cdot \nabla_x g_{GC} = 0 \quad + \text{Poisson.}$$

# Vlasov-Poisson: long and short time equations

- 1 **Long** time ( $\sim 1/\varepsilon$ ) accuracy against the **Guiding Center** model

$$g^\varepsilon(\mathbf{x}, \mathbf{v}, t) = f^\varepsilon\left(\mathbf{x}, \mathbf{v}, \frac{t}{\varepsilon}\right) \Rightarrow \begin{cases} \partial_t g^\varepsilon + \frac{1}{\varepsilon} \left( \mathbf{v} \cdot \nabla_{\mathbf{x}} g^\varepsilon + \left( \mathcal{E}^\varepsilon + \frac{1}{\varepsilon} \mathbf{v}^\perp \right) \cdot \nabla_{\mathbf{v}} g^\varepsilon \right) = 0 \\ + \text{Poisson} \end{cases}$$

When  $\varepsilon \rightarrow 0$  then  $\int g^\varepsilon d\mathbf{v} \rightarrow g_{GC}$  where

$$\partial_t g_{GC} + \mathbf{E}^\perp \cdot \nabla_{\mathbf{x}} g_{GC} = 0 \quad + \text{Poisson.}$$

(Golse–Saint-Raymond 1999; Frénod–Sonnendrücker 2000, Bostan 2010)

- 2 **Short** time ( $\sim 1$ ) accuracy against the short time **Guiding Center** model

$$f_{GC}^\varepsilon(\mathbf{x}, t) = g_{GC}(\mathbf{x}, \varepsilon t) \Rightarrow \begin{cases} \partial_t f_{GC}^\varepsilon + \varepsilon \mathbf{E}^\perp \cdot \nabla_{\mathbf{x}} f_{GC}^\varepsilon = 0 \\ + \text{Poisson} \end{cases}$$

# Vlasov-Poisson: short and long time simulations

- 1 **Short** test case: Landau damping (periodic boundary condition on  $[0, 4\pi] \times [0, 1]$ )

$$f_0(\mathbf{x}, \mathbf{v}) = \frac{1}{2\pi} \left( 1 + 0.1 \cos(x_1/2) \right) \exp\left(-\frac{v_1^2 + v_2^2}{2}\right).$$

- 2 **Long** test case: Kelvin-Helmholtz (periodic boundary condition on  $[0, 4\pi] \times [0, 2\pi]$ )

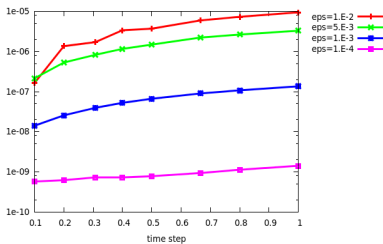
$$f_0(\mathbf{x}, \mathbf{v}) = \frac{1}{2\pi T_1 T_2} \left( \sin(x_2) + 0.05 \cos(x_1/2) \right) \exp\left(-\frac{v_1^2 + v_2^2}{2}\right).$$

Global errors in time of the  $L_2([0, T_1] \times [0, T_2])$  norm of the densities

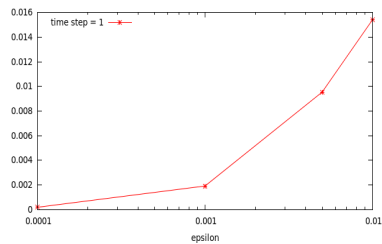
# 4d VP: Global errors at time = 4

Short time simulations: comparisons with

a reference solution ( $\Delta t = 2\pi\epsilon/100$ )



the (short time) Guiding Center model

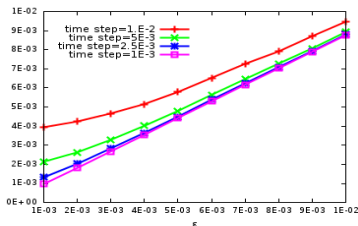
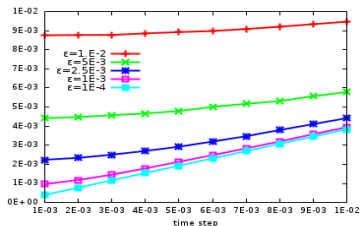


	$\Delta t = 1E-1$	$\Delta t = 2E-1$	$\Delta t = 5E-1$	$\Delta t = 8E-1$	$\Delta t = 1$
$\epsilon = 1.E-2$	1	3	7	12	15
$\epsilon = 1.E-3$	15	31	79	127	159
$\epsilon = 1.E-4$	159	318	795	1273	1591

**Table:** The whole number of rapid full tours enclosed in a time step of the scheme

# 4d VP: Global errors at time = 5

## Long time simulations : Kelvin-Helmholtz instability



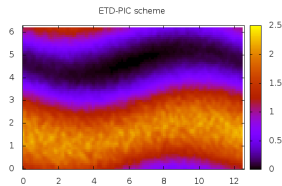
## Asymptotic Preserving behaviour with respect to the **Guiding Center model**

	$\Delta t=1E-3$	$\Delta t=3E-3$	$\Delta t=5E-3$	$\Delta t=7E-3$	$\Delta t=1E-2$
$\epsilon = 5.E-3$	6	19	31	44	63
$\epsilon = 2.5E-3$	25	76	127	178	254
$\epsilon = 1.E-3$	159	477	795	1114	1591
$\epsilon = 1.E-4$	15915	47746	79577	111408	159154

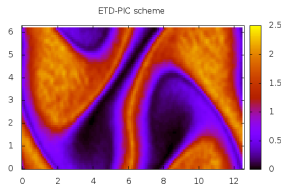
**Table:** The whole number of rapid full tours enclosed in a time step of the scheme

# $\varepsilon$ -Vlasov-Poisson solution vs. Guiding Center solution

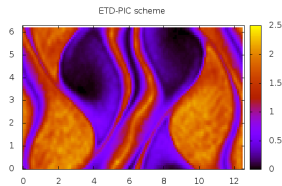
$\Delta t = 0.01$ ,  $\varepsilon = 0.005$  ( $N = 63$ )    the scheme  $\uparrow$     Guiding Center  $\downarrow$  densities



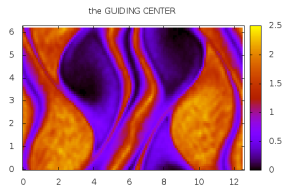
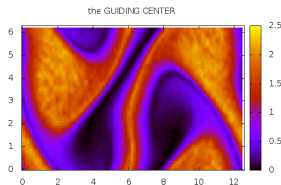
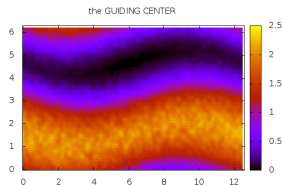
$t_f = 5$



15



20



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# Aim

- 1 Compare the time scheme to a reference solution of the oscillatory Vlasov-Poisson system in long time.
- 2 **Additional aim:** Show numerically the convergence result (Vlasov-Poisson vs. guiding center simulations)
- high computational cost for the reference solution (classical time schemes)

## Difficulties:

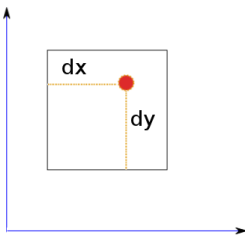
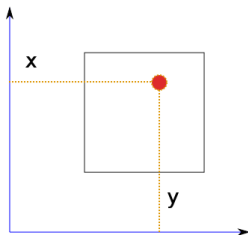
- we address noise by using a large number of particles.
- conventional PIC suffers from often data motion (memory/CPU).
- need to optimize the PIC implementation  
K. J. Bowers: J. Comput. Phys. (2001).  
D. Tskhakaya, R. Schneider: J. Comput. Phys. (2007).

Implementation in [SeLaLib](http://selalib.gforge.inria.fr/) (the Semi Lagrangian Library),  
<http://selalib.gforge.inria.fr/>

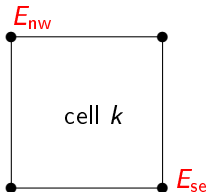


# Main ingredients (1/2)

**Data structures:** data used together should be stored together



```
type :: sll_particle_2d
  sll_int32  :: ic
  sll_real32 :: dx
  sll_real32 :: dy
  sll_real64 :: vx
  sll_real64 :: vy
  sll_real32 :: q
end type sll_particle_2d
```



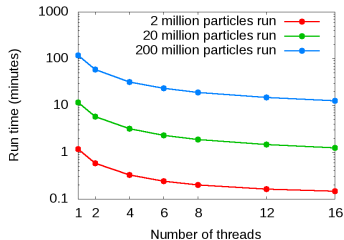
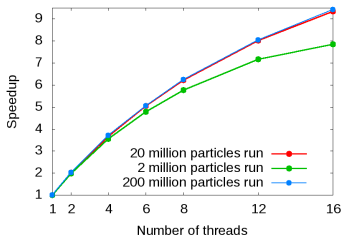
```
type charge_accumulator_cell_2d
  sll_real64 :: q_sw
  sll_real64 :: q_se
  sll_real64 :: q_nw
  sll_real64 :: q_ne
end type charge_accumulator_cell_2d
```

## Main ingredients (2/2)

- 1 Cell index + local offset for particle representation:
  - reduced memory size
  - reduces the nb of arithmetical operations during the interpolation and the charge deposition
- 2 Cell-based  $\mathbf{E}$  and  $\rho$ :
  - allows to advance particles with a minimum of accessed memory streams.
  - additional steps to convert to/from grid arrays:  $\mathbf{E}_{i,j} \longrightarrow \mathbf{E}_{accum}(k)$  and  $\rho_{accum}(k) \longrightarrow \rho_{i,j}$  (the cost is  $\sim$  to  $N_{cells}$ )
- 3 Particle sorting (to be done periodically):
  - maximize sequential particle processing
- 4 Parallelization: multiprocessing (MPI) + multithread (OpenMP)

# Performance: speedup

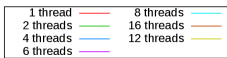
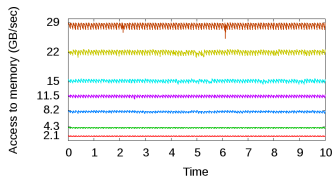
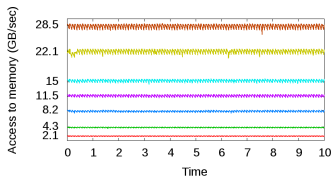
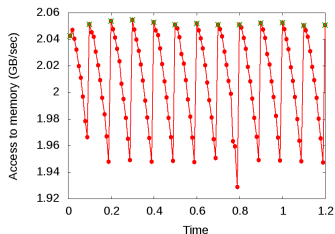
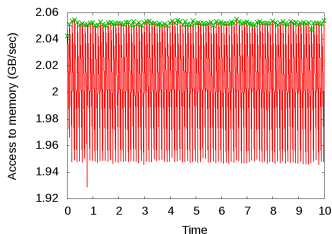
Landau damping test-case 1000 iterations, a grid of 512 x 16 cells.  
 Verification: conservation of the total energy, electric field energy.



Threads	Time (seconds)	Speedup
1	703.2	1.0
2	348.2	2.02
4	191.5	3.67
6	139.2	5.05
8	112.9	6.23
12	87.7	8.02
16	75.3	9.34

# Performance: memory bandwidth

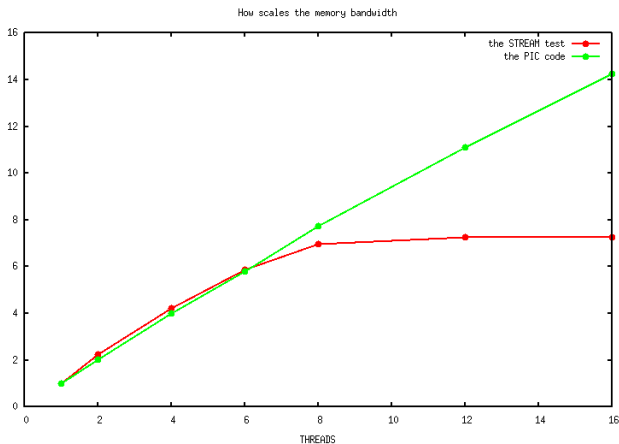
$N$  (nb of loads/stores) \* 32B/time of particle push



2 million (left) and 20 million (right) particles runs.

## Performance: MB Stream benchmark

The stream test : 10 GB/s on single core and 75 GB/s /16 threads.  
Use of 2 processes and several threads.  
20 million particles run.



# Performance

Million of particles processed per second :  $N_p * N_{iter} / T$ .

Simulation \ Threads	1	2	4	8	16
2 million particles	28.5	56.8	101.7	165.2	224.3
20 million particles	28.4	57.4	104.4	177.1	265.6
200 million particles	28.0	56.9	103.5	174.4	263.8

# Vlasov-Poisson/guiding center model

Long time ( $\sim 1$ ) simulations of

$$\begin{cases} \partial_t g^\varepsilon + \frac{1}{\varepsilon} \left( \mathbf{v} \cdot \nabla_{\mathbf{x}} g^\varepsilon + \left( \mathcal{E}^\varepsilon + \frac{1}{\varepsilon} \mathbf{v}^\perp \right) \cdot \nabla_{\mathbf{v}} g^\varepsilon \right) = 0 \\ + \text{Poisson} \end{cases}$$

and the limit model

$$\partial_t g_{GC} + \mathbf{E}^\perp \cdot \nabla_{\mathbf{x}} g_{GC} = 0 \quad + \text{Poisson.}$$

**Kelvin-Helmholtz instability:** periodic-periodic boundary conditions on  $[0, 4\pi] \times [0, 2\pi]$ , Poisson (solved by FFT). Random initialization of

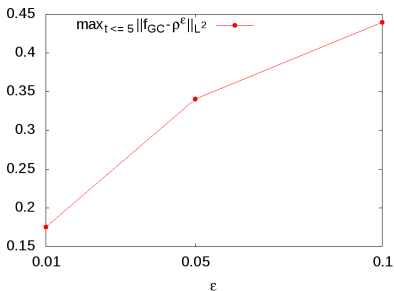
$$f_0(\mathbf{x}, \mathbf{v}) = \frac{1}{2\pi} \left( \sin(x_2) + 0.05 \cos(x_1/2) \right) \exp \left( -\frac{v_1^2 + v_2^2}{2} \right).$$

## Numerical results

10 million particles,  $256 \times 128$  cells.

- for VP: Reference solution with leap-frog,  $\delta t = 2\pi\epsilon^2/80$
- for GC: RK2 with  $\Delta t = 0.01$ .

Global error at time  $t = 5$ :  $\|g_{GC} - \rho^\epsilon\|_{L^2}$

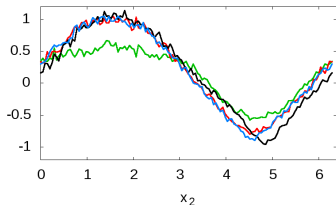




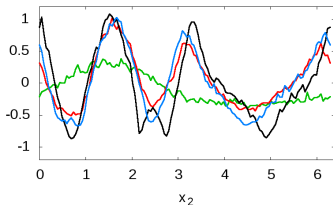
# Numerical results

guiding center, VP with  $\varepsilon = 0.05$ , VP with  $\varepsilon = 0.1$ , VP with  $\varepsilon = 0.5$

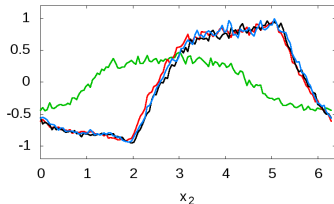
Densities at  $x_1=0$  and time = 12



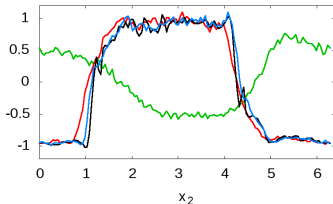
Densities at  $x_1=0$  and time = 22



Densities at  $x_1=\pi$  and time = 12



Densities at  $x_1=\pi$  and time = 22



## Conclusion and Outlook

- E. Frénod, S.H., M. Lutz, E. Sonnendrücker, CiCP, 2015.
- E. Chacon-Golcher, S. H., M. Lutz, preprint HAL.

Short and long time simulation for oscillatory 4d Vlasov-Poisson:

- allows large time steps with respect to the rapid period.
- produce accurate numerical solutions for different small values of  $\varepsilon$  with the same computational cost.
- achieve high efficiency in PIC simulation with many particles.
- compute reference solution for oscillatory VP with accuracy.
  
- compare the time scheme to a reference solution in long time.
- consider slowly varying magnetic field  $B$ .
- improve the algorithm
- towards the 6d model

THANK YOU !